



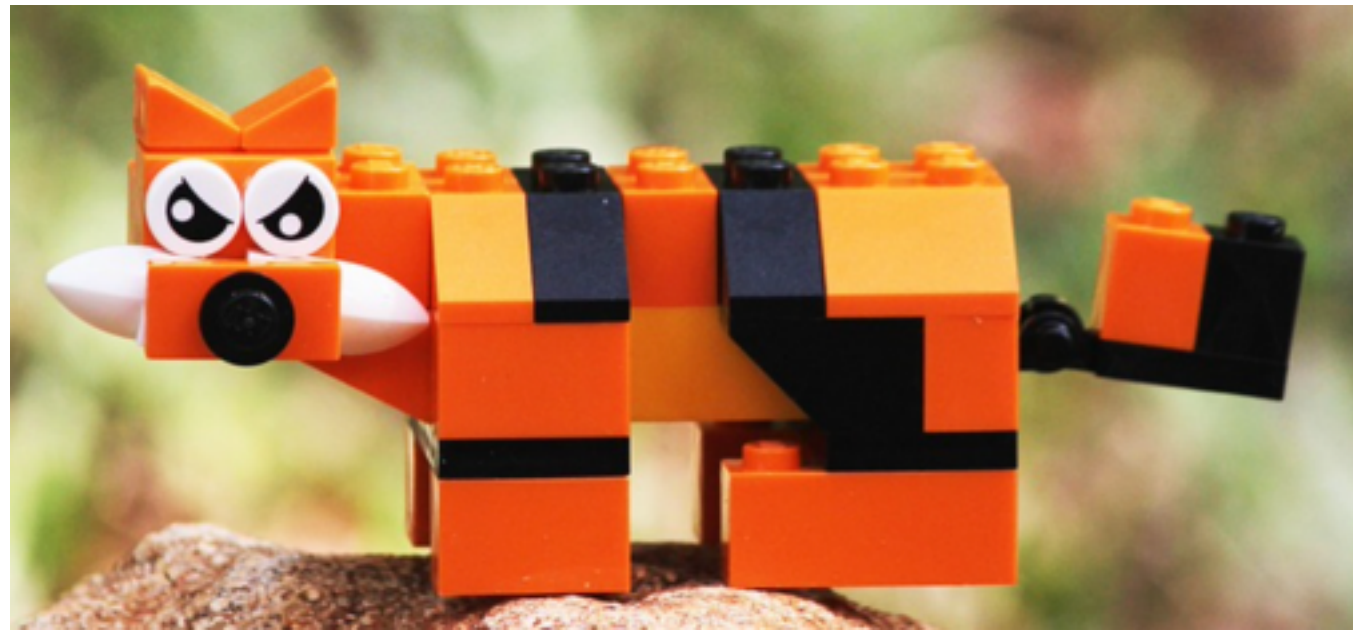
Modeling in CP

Bin-Packing Case Study

Modeling is an Art

- Modeling a real world problem with variables, domains and constraints

Model

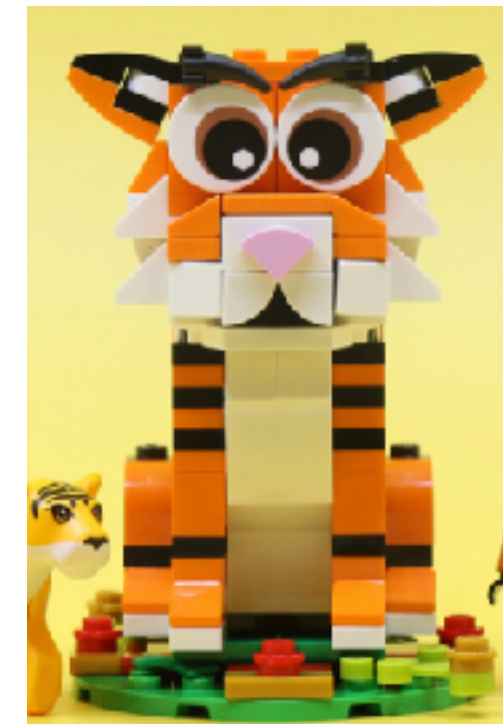
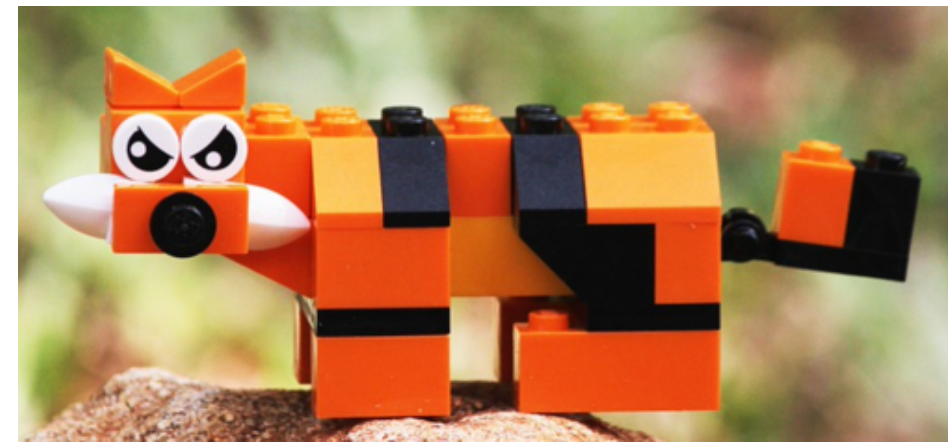


Real world problem



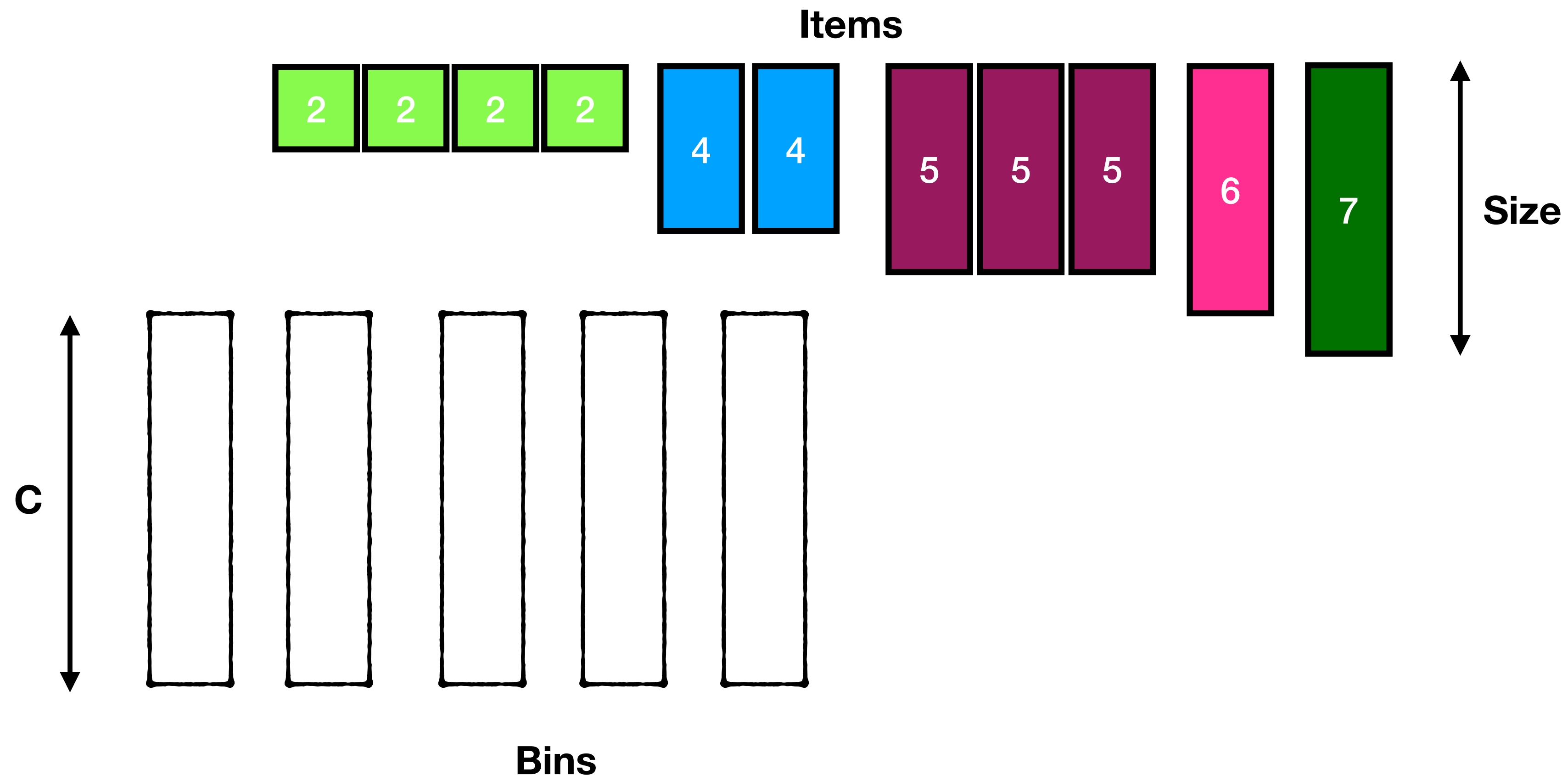
Modeling is an Art

- ▶ For a same problem, many different models
 - Variables, domains and constraints
- ▶ The model can have dramatic effect on the solving time



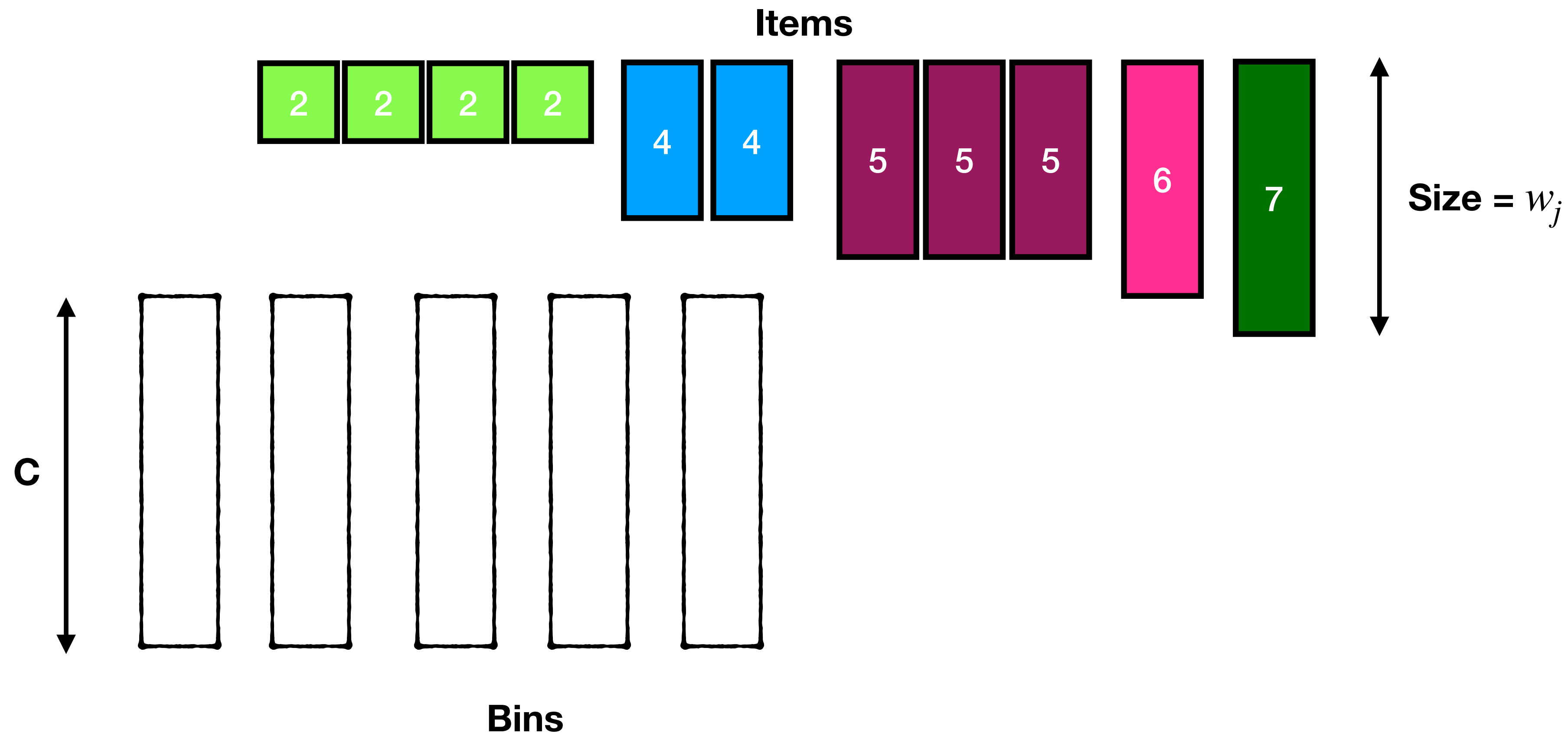
Case Study: Bin Packing

- ▶ Given n items, the size of each item
- ▶ Given m bins, each with a same capacity c
- ▶ Find a bin for each object such that the capacity of the bins is respected



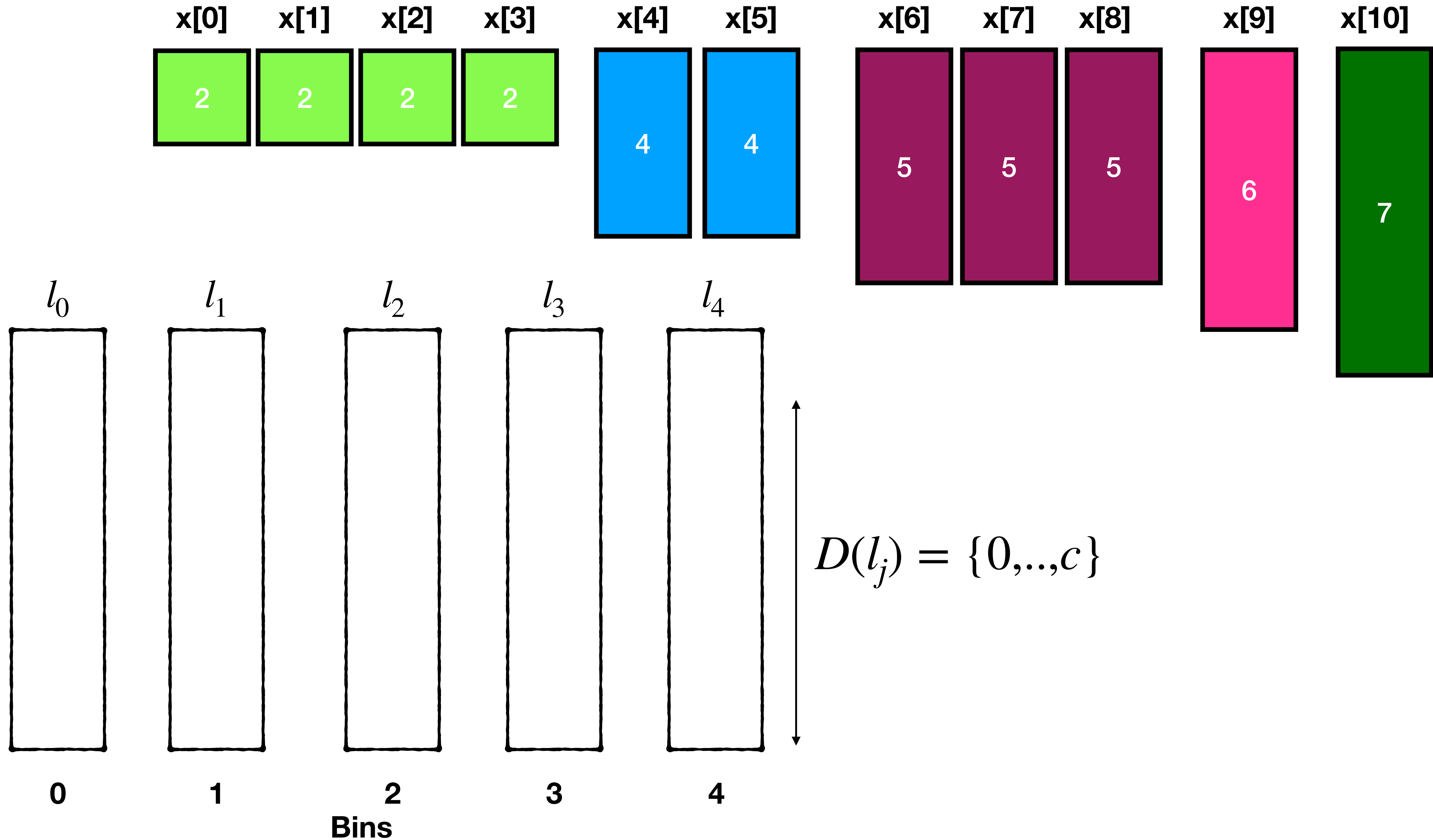
Decision variable ?

- ▶ Item point of view: in what bin do we place each item
- ▶ Bin point of view: what are the set of items allocated to each bin (set variable, more complex)

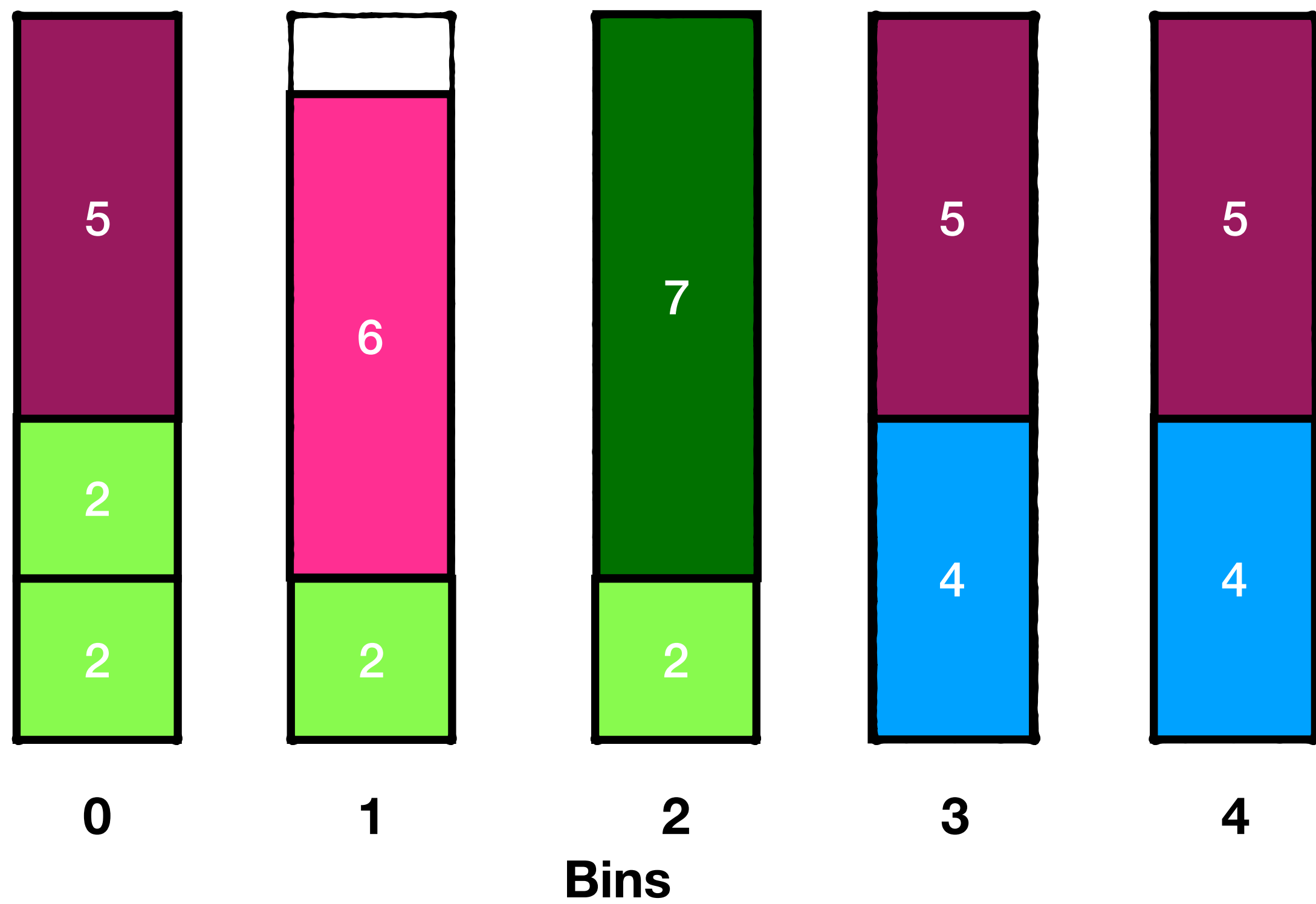
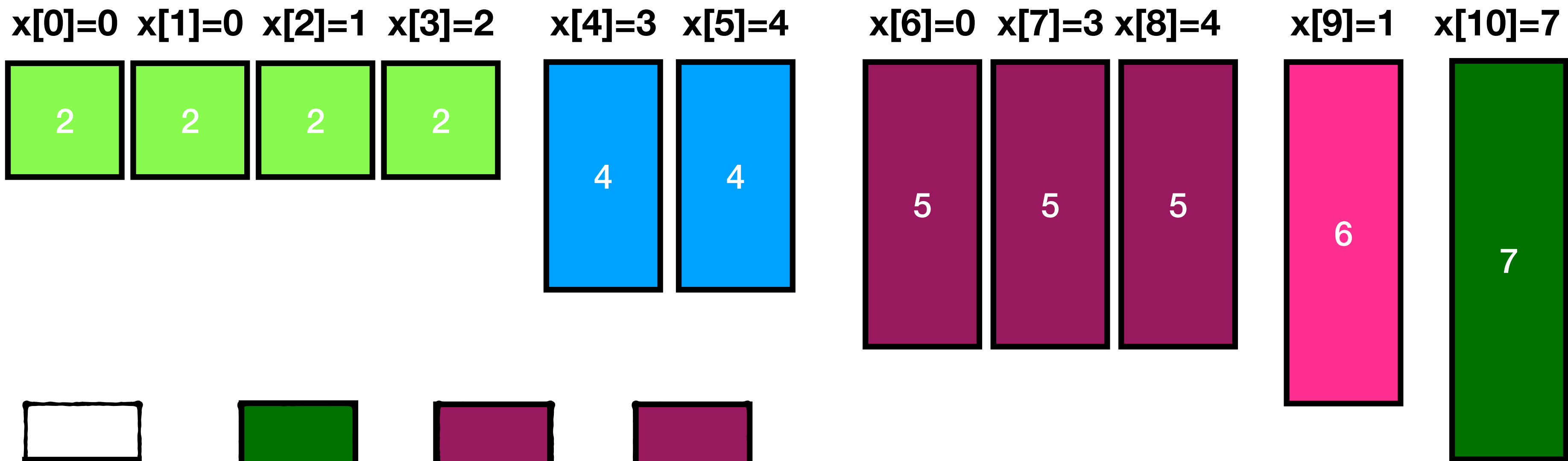


Decision variables and Domains

$$D(x_i) = \{0, 1, 2, 3, 4\}$$



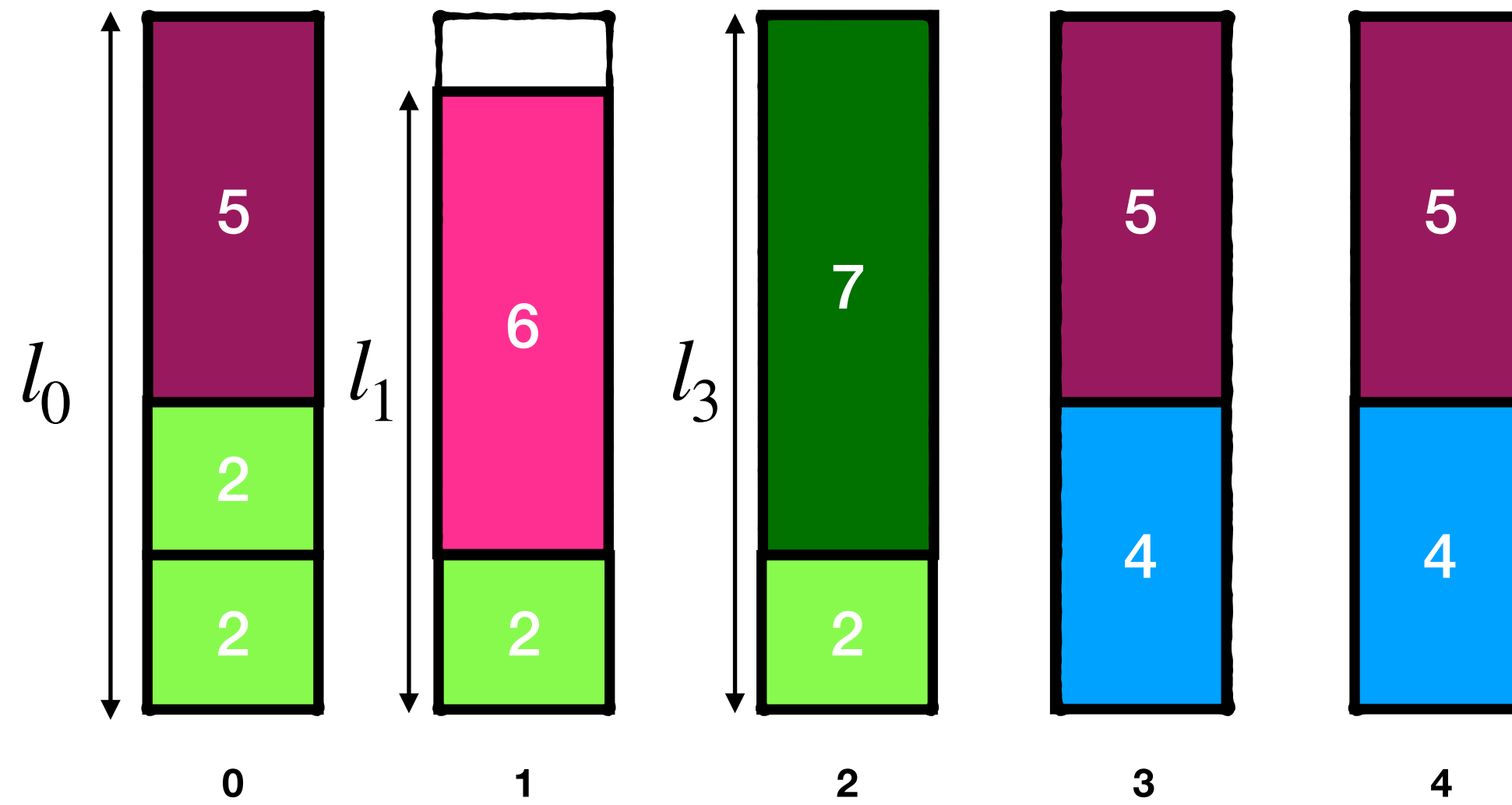
Solution



Constraints

$$\forall j \in [1..m] : l_j = \sum_{i \in [1..n]} (x_i = j) \cdot w_i$$

$$D(l_j) = \{0, \dots, c\}$$



Bin-Packing Model

```

int capa = 9;
int [] items = new int[] {2,2,2,2,4,4,5,5,5,6,7};

int nBins = 5;
int nItems = items.length;

Solver cp = makeSolver();
IntVar [] x = makeIntVarArray(cp, nItems, nBins);
IntVar [] l = makeIntVarArray(cp, nBins, capa+1);

BoolVar [][] inBin = new BoolVar[nBins][nItems]; // inBin[j][i] = 1 if item i is placed in bin
j
// bin packing constraint
for (int j = 0; j < nBins; j++) {
    for (int i = 0; i < nItems; i++) {
        inBin[j][i] = isEqual(x[i], j);
    }
}
for (int j = 0; j < nBins; j++) {
    IntVar[] wj = new IntVar[nItems];
    for (int i = 0; i < nItems; i++) {
        wj[i] = mul(inBin[j][i], items[i]);
    }
    cp.post(sum(wj, l[j]));
}

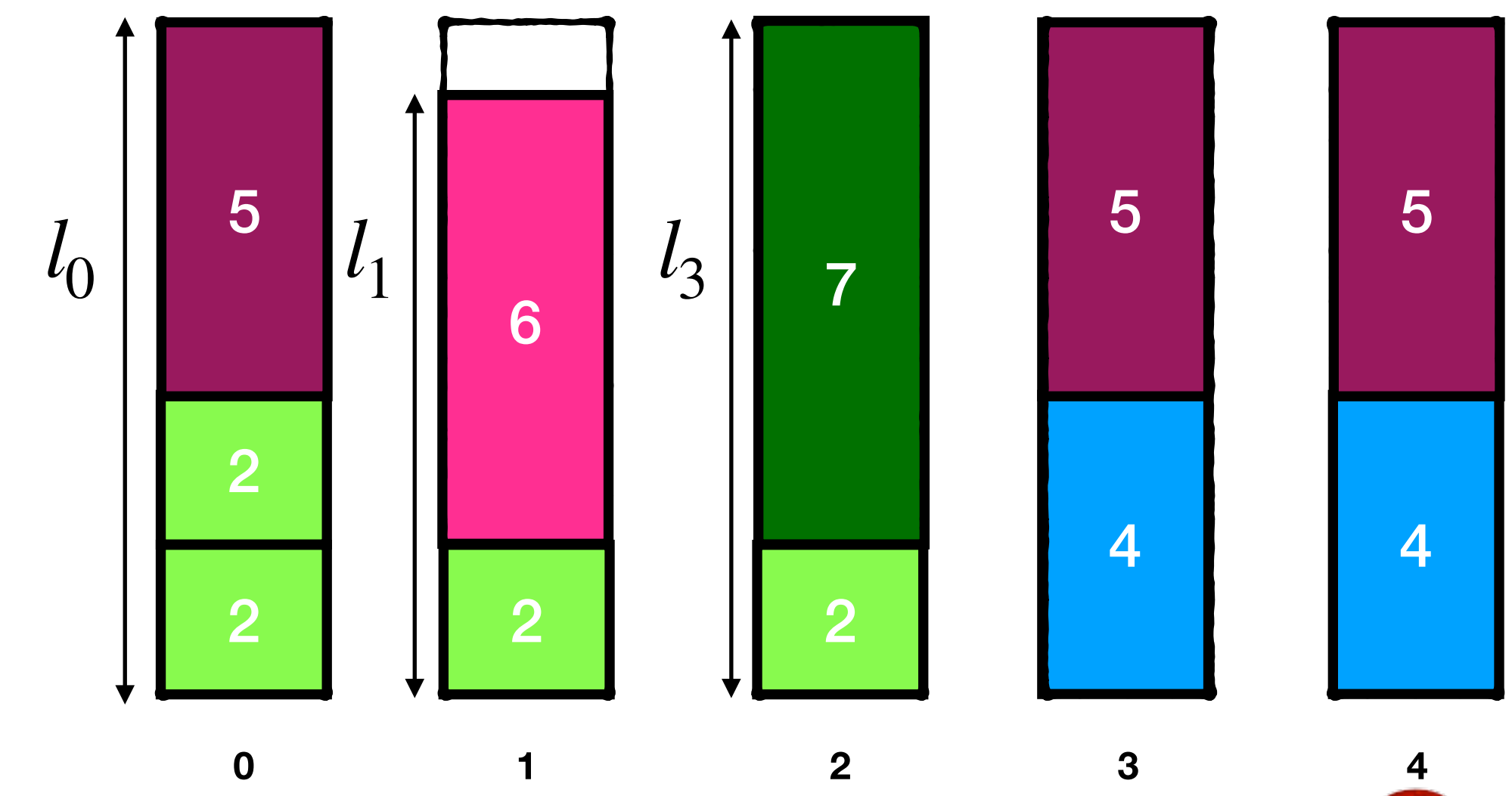
DFSearch dfs = makeDfs(cp, firstFail(x));

```

$$l_j = \sum_{i \in [1..n]} (x_i = j) \cdot w_i$$

Global Constraints for Bin-Packing

$$\forall j \in [1..m] : l_j = \sum_{i \in [1..n]} (x_i = j) \cdot w_i$$



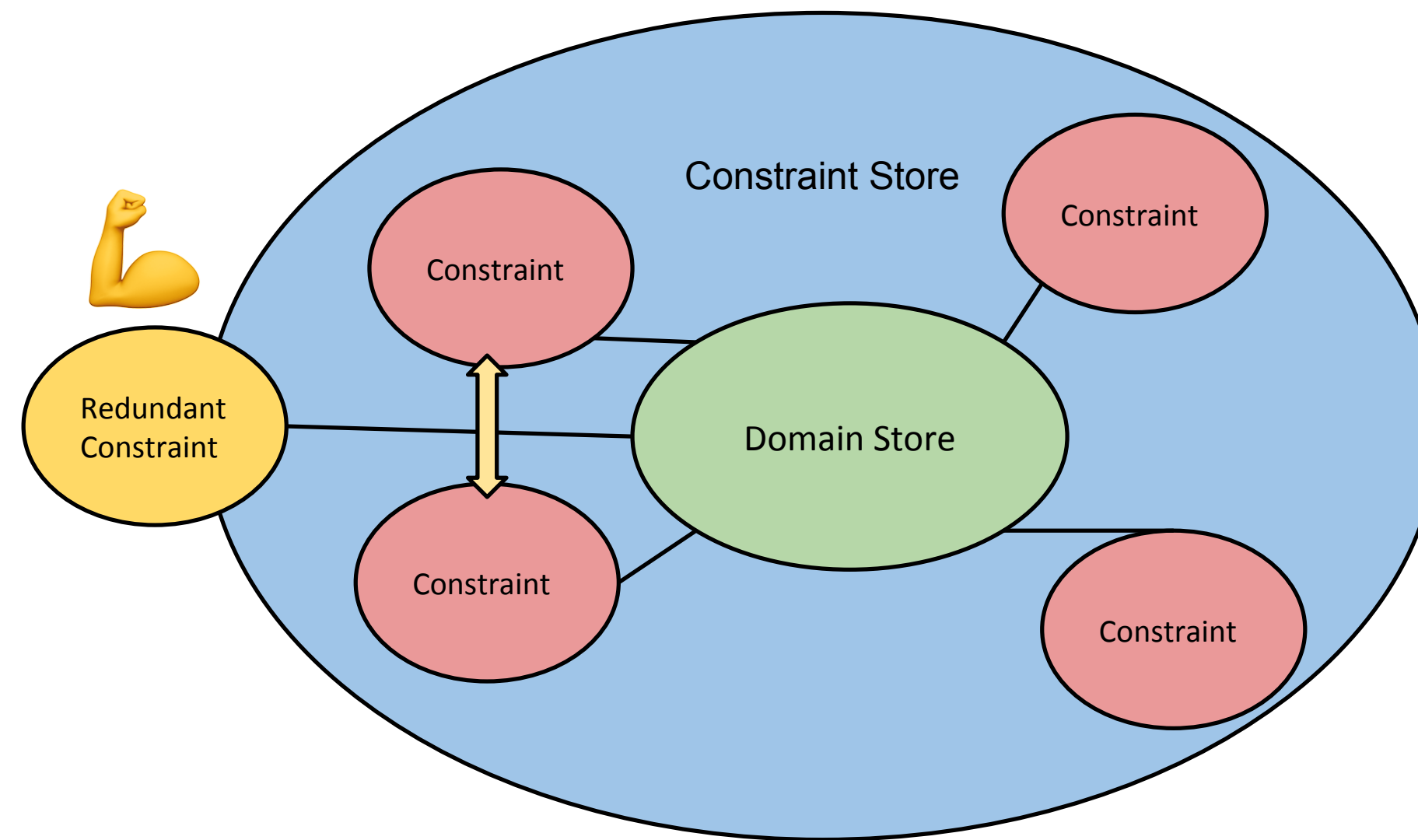
► This kind of constraint is very frequent, most of the solvers call it **BinPacking**($[l_1, \dots, l_m], [x_1, \dots, x_n], [w_1, \dots, w_n]$)



- Shaw, Paul. "A constraint for bin packing." CP 2004.
- Schaus, Pierre. "Solving balancing and bin-packing problems with constraint programming." *PhD Thesis* (2009)

Redundant Constraints

- ▶ Redundant Constraints:
 - Do not exclude any previous solution
 - Improve the pruning of the search space (better communication between constraints)



How to find redundant constraints for your model ?

- ▶ Express properties of the solution
- ▶ Derive consequences of (combinations of) constraints
- ▶ BinPacking:

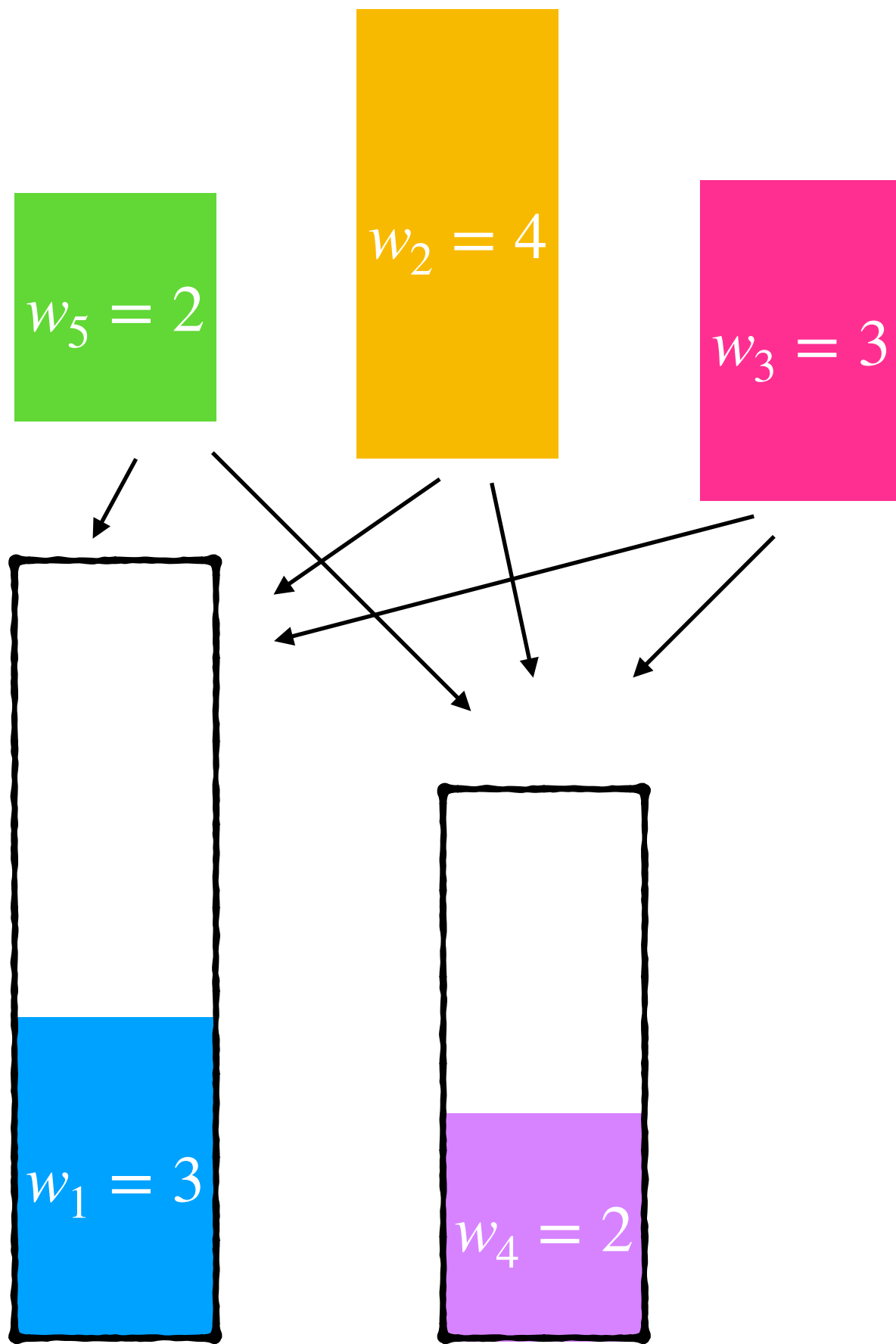
$$\forall j \in [1..m] : l_j = \sum_{i \in [1..n]} (x_i = j) \cdot w_i$$

$$\sum_{j \in [1..m]} l_j = \sum_{i \in [1..n]} w_i$$



Redundant Constraint

Infeasible, but not detected by $\forall j \in [1..m] : l_j = \sum_{i \in [1..n]} (x_i = j) \cdot w_i$



Failure detected by redundant constraints

$$\sum_{j \in [1..m]} l_j = \sum_{i \in [1..n]} w_i$$

$$[3..7] + [2..5] = 14$$

$$[5..12] = 14$$

Bin-Packing Model

```
int capa = 9;
int [] items = new int[] {2,2,2,2,4,4,5,5,5,6,7};

int nBins = 5;
int nItems = items.length;

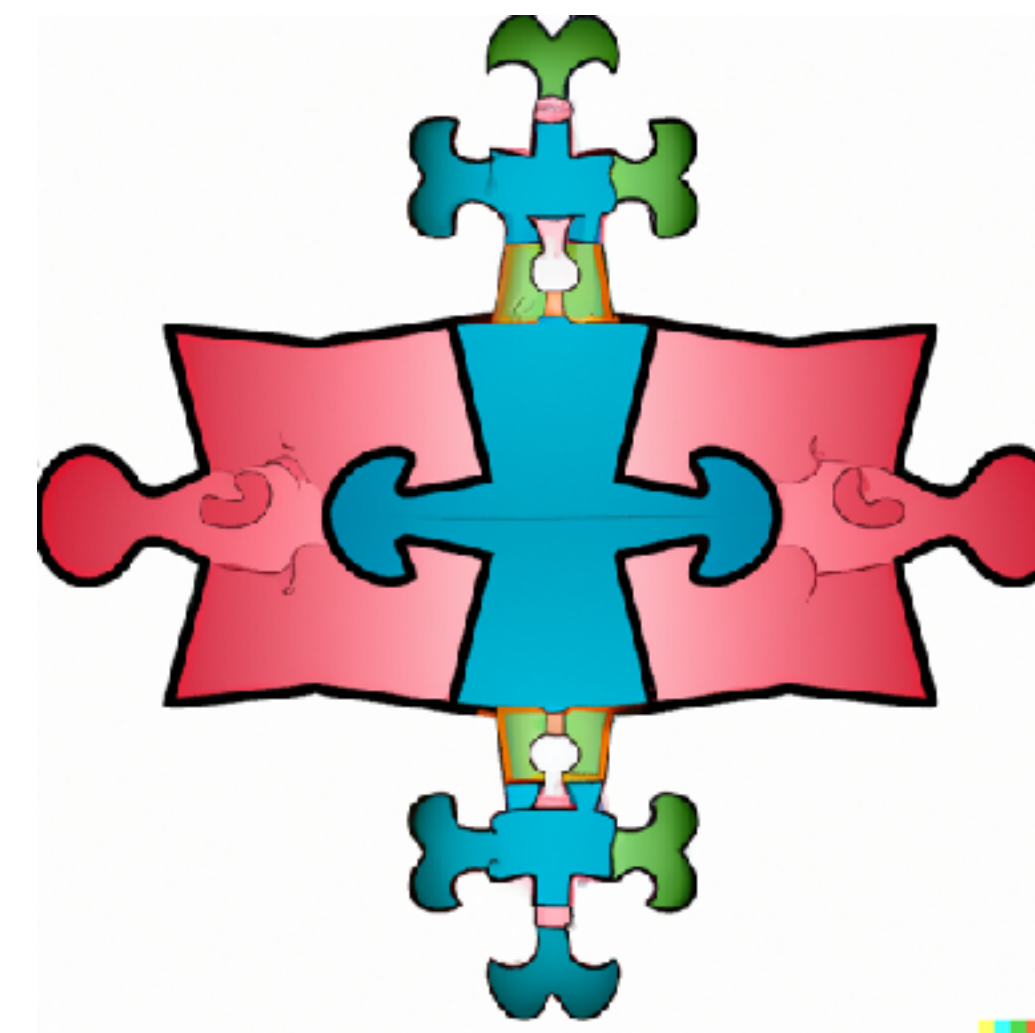
Solver cp = makeSolver();
IntVar [] x = makeIntVarArray(cp, nItems, nBins);
IntVar [] l = makeIntVarArray(cp, nBins, capa+1);

BoolVar [][] inBin = new BoolVar[nBins][nItems]; // inBin[j][i] = 1 if item i is placed in bin j
// bin packing constraint
for (int j = 0; j < nBins; j++) {
    for (int i = 0; i < nItems; i++) {
        inBin[j][i] = isEqual(x[i], j);
    }
}
for (int j = 0; j < nBins; j++) {
    IntVar[] wj = new IntVar[nItems];
    for (int i = 0; i < nItems; i++) {
        wj[i] = mul(inBin[j][i], items[i]);
    }
    cp.post(sum(wj, l[j]));
}

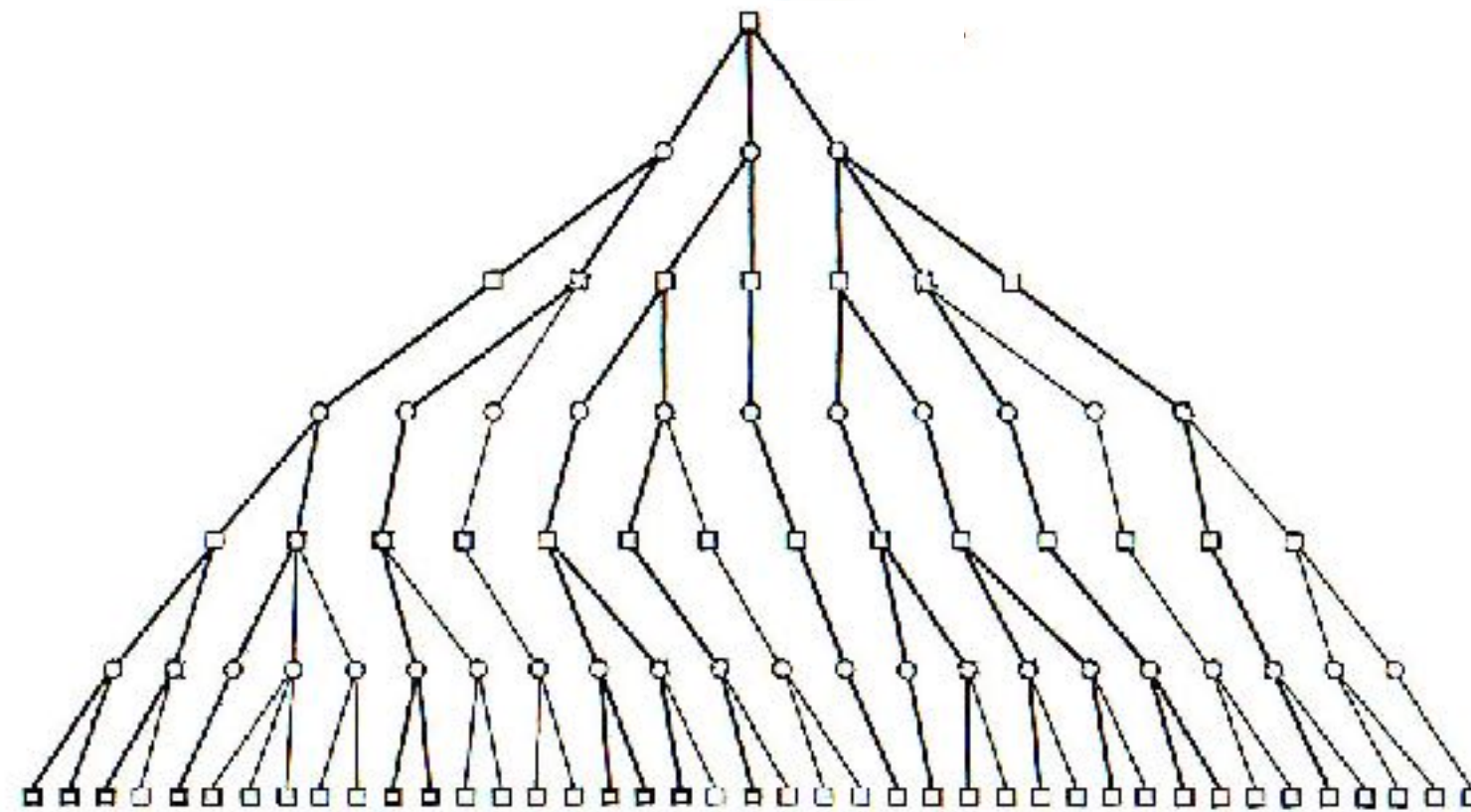
// redundant constraint 🤔
cp.post(sum(l, IntStream.of(items).sum()));
```

Bin-Packing

Symmetries



- ▶ Many problems naturally exhibit symmetries
- ▶ A symmetry maps solutions to solutions and non-solutions to non-solutions
- ▶ Symmetries leads to symmetrical search spaces
- ▶ Exploring symmetrical search spaces is useless
 - If no solution in one, no solution in the other



Detect and remove symmetries (dynamic or static)
only inspect one (non-)solution in each equivalence class

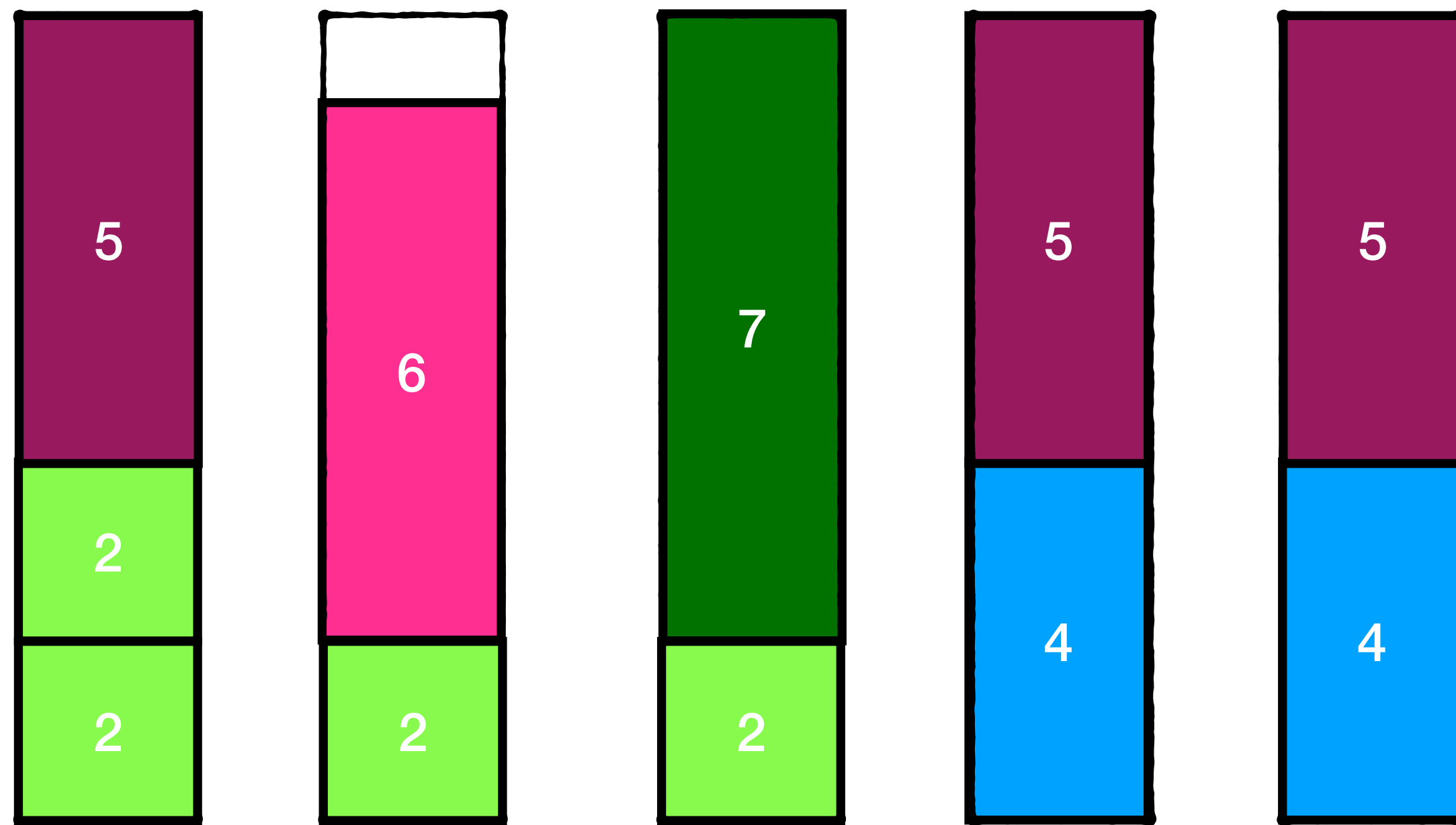
A value symmetry is a bijection σ on values mapping (non-)solutions to (non-)solutions:

$$\begin{array}{ccc} x_1, x_2, \dots, x_n & \xleftrightarrow{\sigma} & x_{\sigma(1)}, x_{\sigma(2)}, \dots, x_{\sigma(n)} \\ a_1, a_2, \dots, a_n & & \sigma(a_1), \sigma(a_2), \dots, \sigma(a_n) \end{array}$$

Value symmetries change the values

Bin-Packing (value) Symmetries

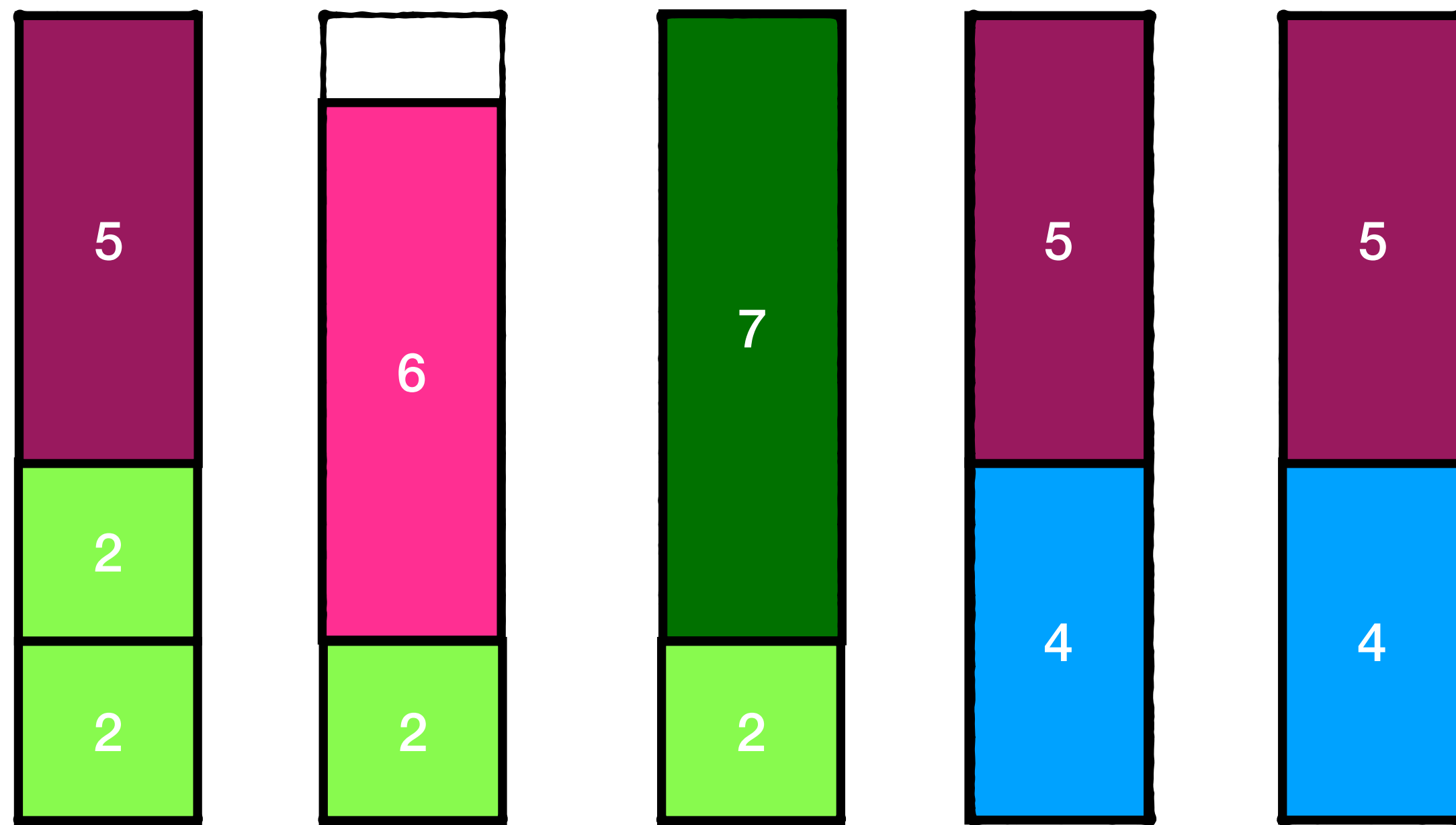
- Interchanging bins is still a valid solution



Bins

Value symmetry breaking

- ▶ Solution: Impose an order on the bins
- ▶ For example: increasing loads $l[0] \leq l[1] \leq l[2] \leq l[3] \leq l[4]$
- ▶ Does not remove all symmetries in case of ties



Bins

Better: Lexicographic Constraints

- Impose a total order on bins (no ties)

```

BoolVar [][] inBin = new BoolVar[nBins][nItems]; // inBin[j][i] = 1 if item i is placed in bin j
// bin packing constraint
for (int j = 0; j < nBins; j++) {
    for (int i = 0; i < nItems; i++) {
        inBin[j][i] = isEqual(x[i], j);
    }
}
for (int j = 0; j < nBins-1; j++) {
    cp.post( inBin[j] ≤ inBin[j+1]);
}

```



Lexicographic
Ordering

Frisch, A., Hnich, B., Kiziltan, Z., Miguel, I., & Walsh, T. (2002, September). Global constraints for lexicographic orderings. CP2002

Variable Symmetry

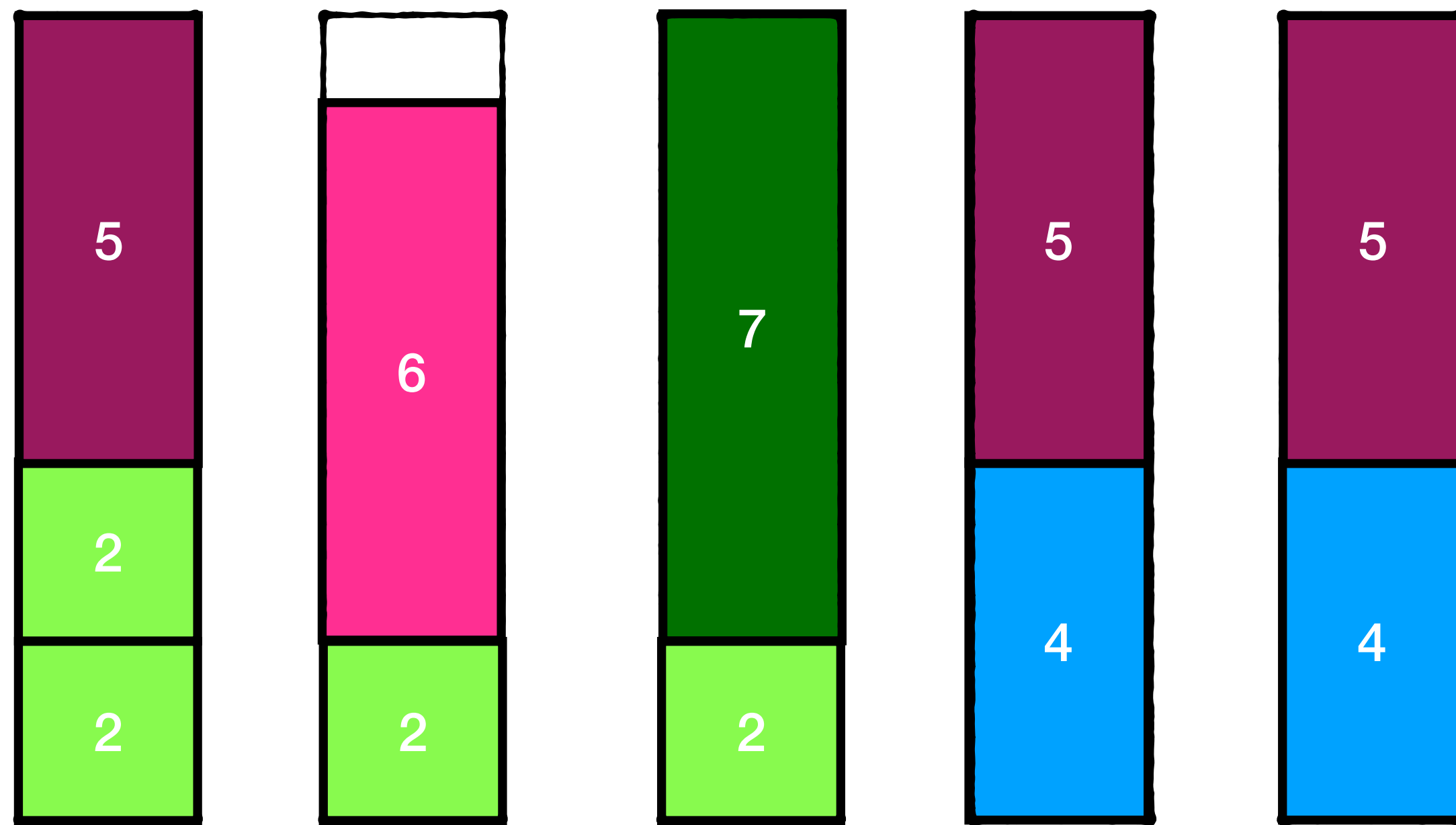
A variable symmetry is a bijection σ on variables mapping (non-)solutions to (non-)solutions:

$$\begin{array}{ccc} x_1, x_2, \dots, x_n & \xleftrightarrow{\sigma} & x_{\sigma(1)}, x_{\sigma(2)}, \dots, x_{\sigma(n)} \\ a_1, a_2, \dots, a_n & & a_1, a_2, \dots, a_n \end{array}$$

Variable symmetries swap the variables

Bin-Packing (variable) Symmetries

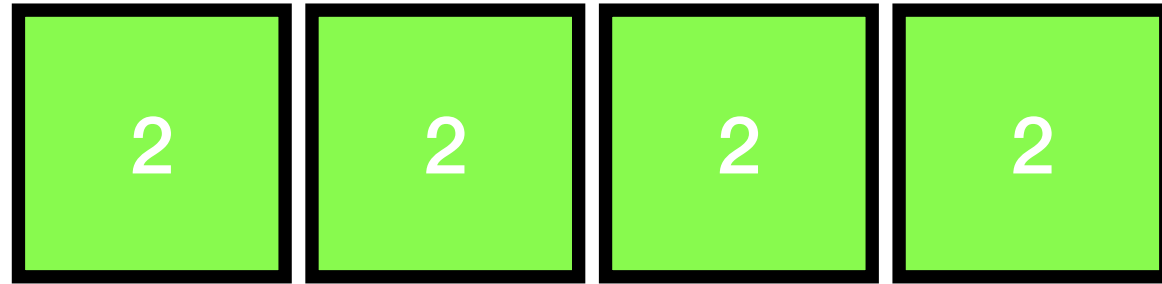
- Exchanging similar items



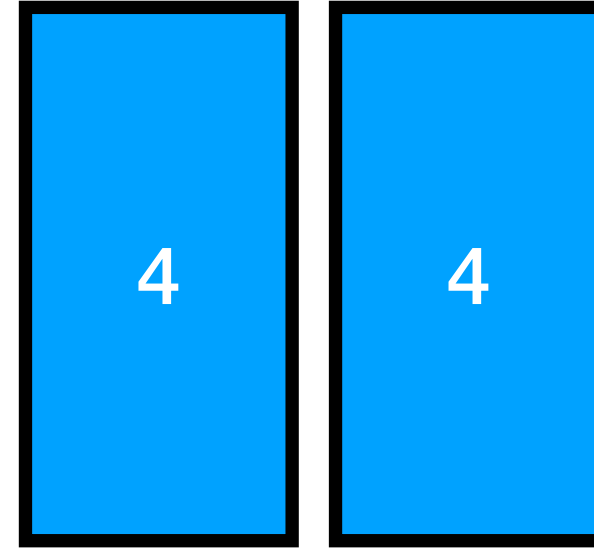
Bins

Bin-Packing: Breaking variable symmetries

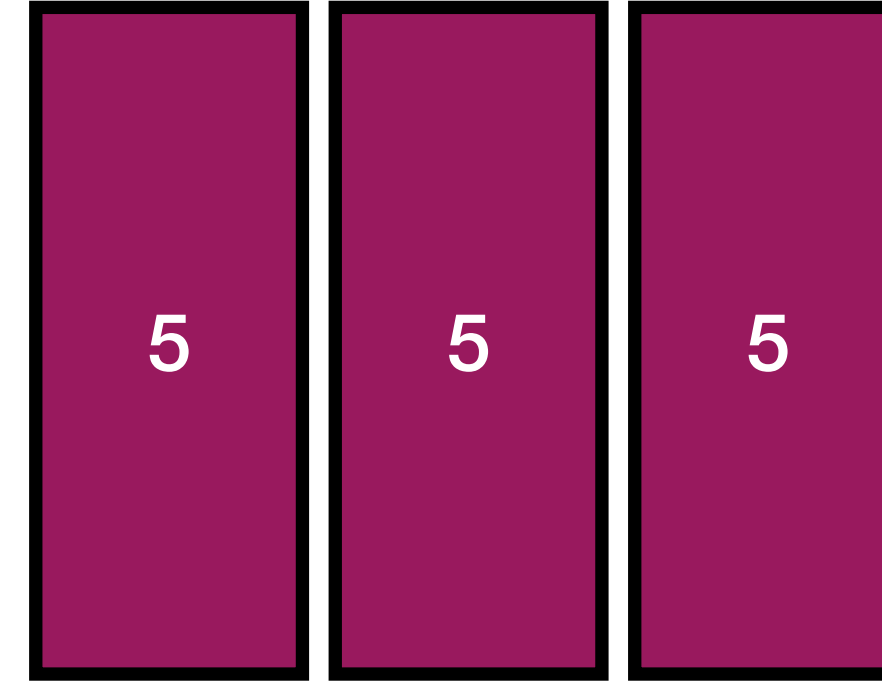
$$x[0] \leq x[1] \leq x[2] \leq x[3]$$



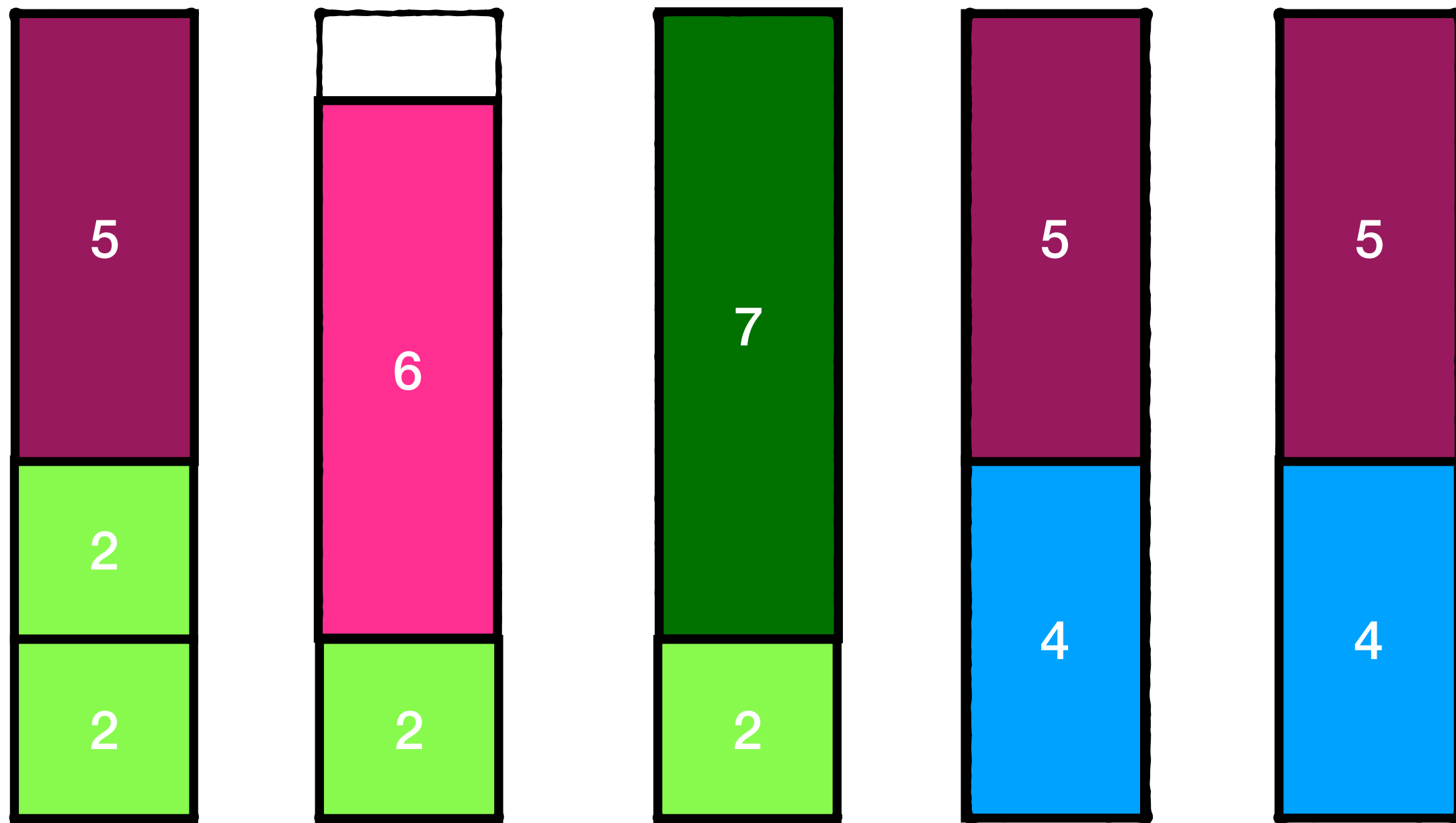
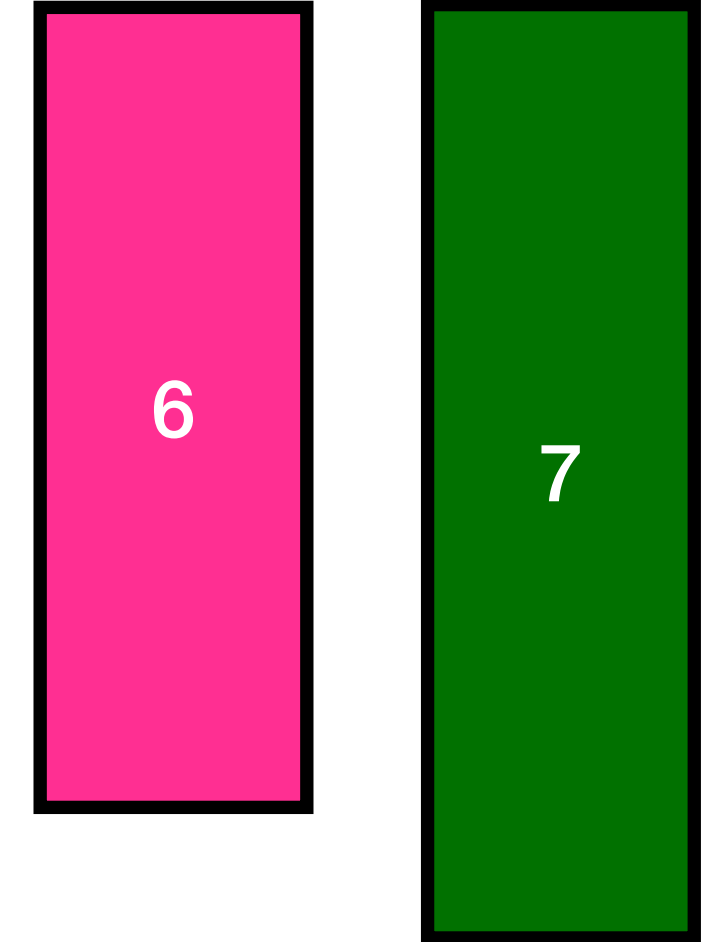
$$x[4] \leq x[5]$$



$$x[6] \leq x[7] \leq x[8]$$




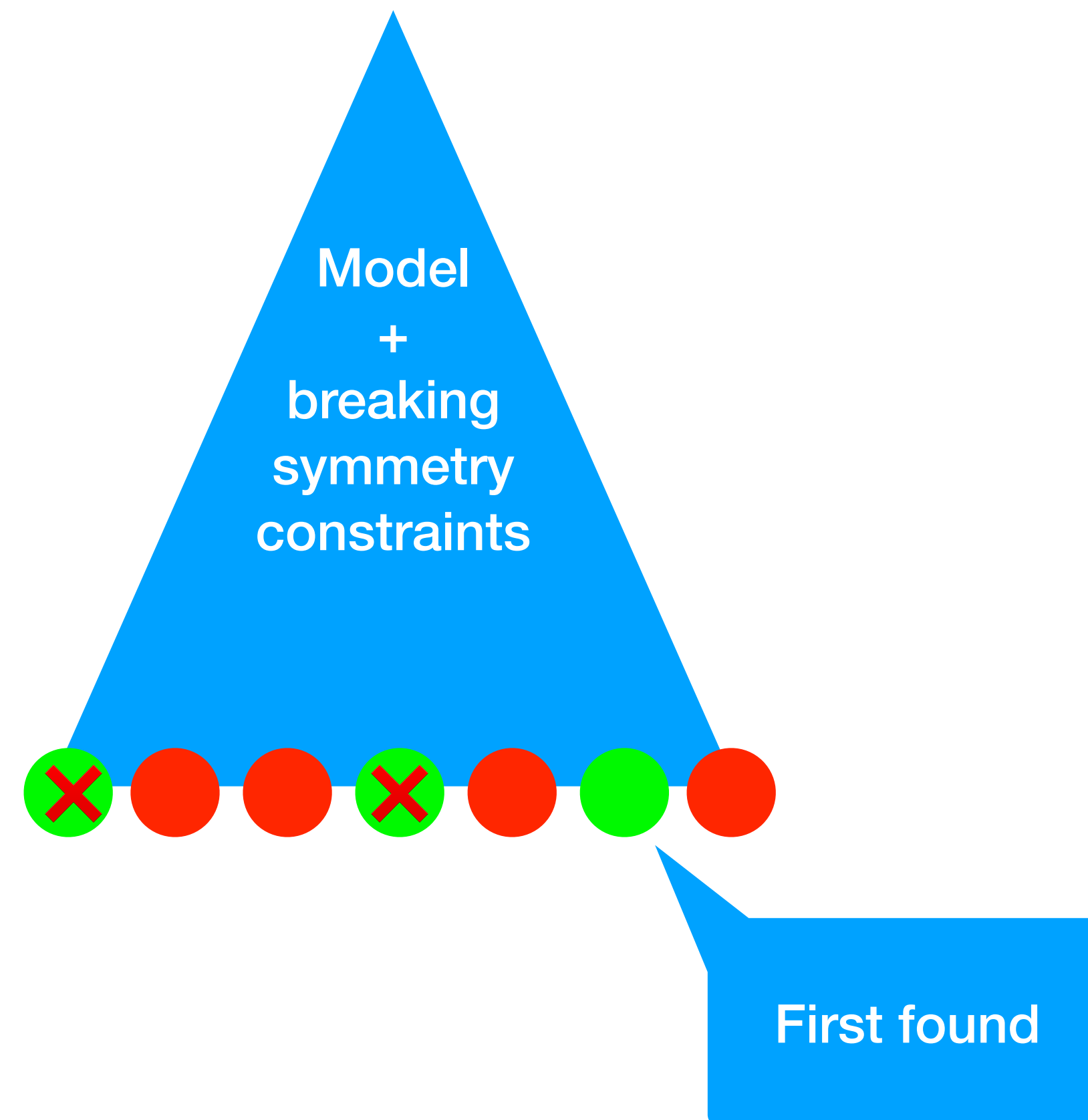
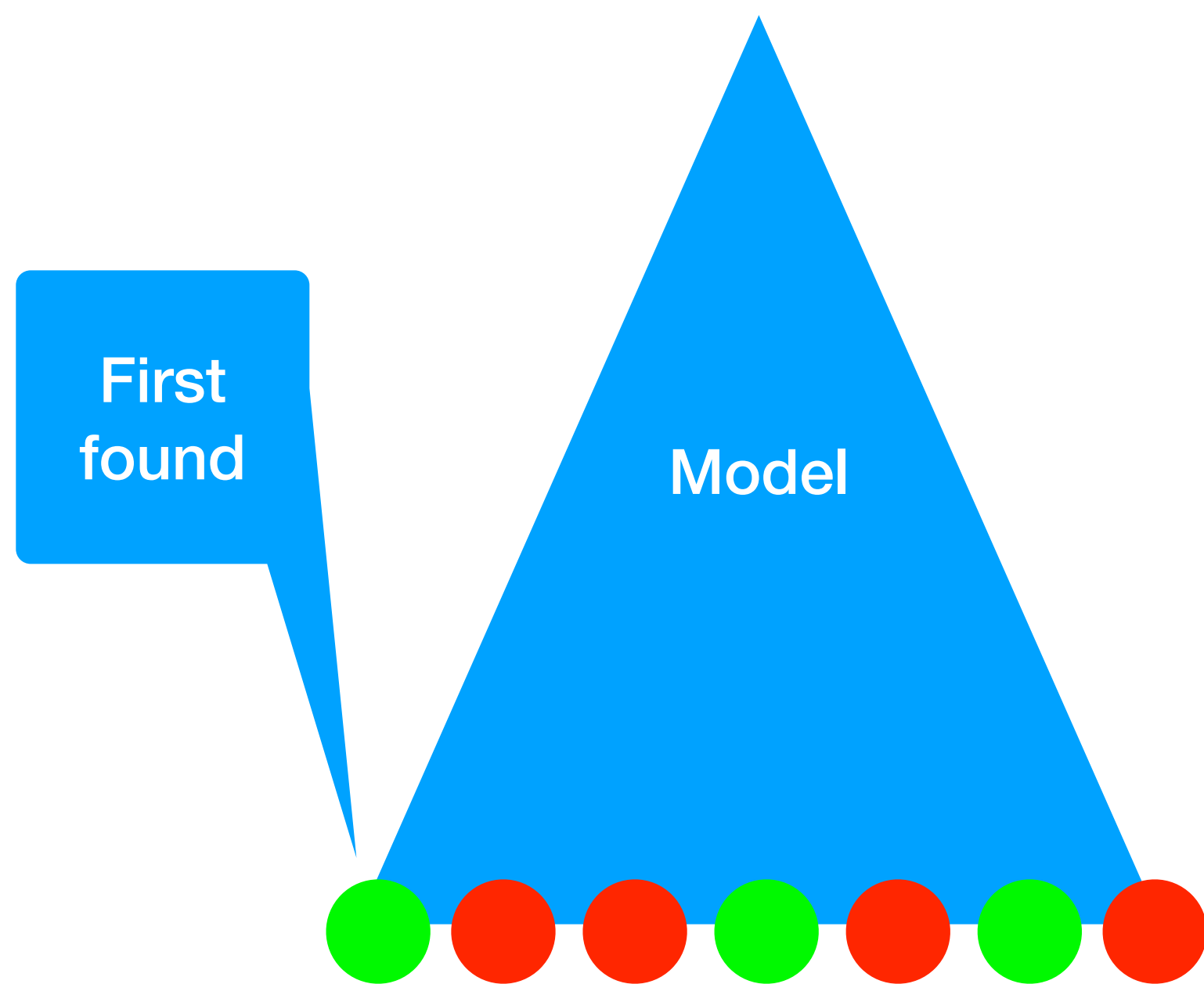
$$x[9] \leq x[10]$$



Bins

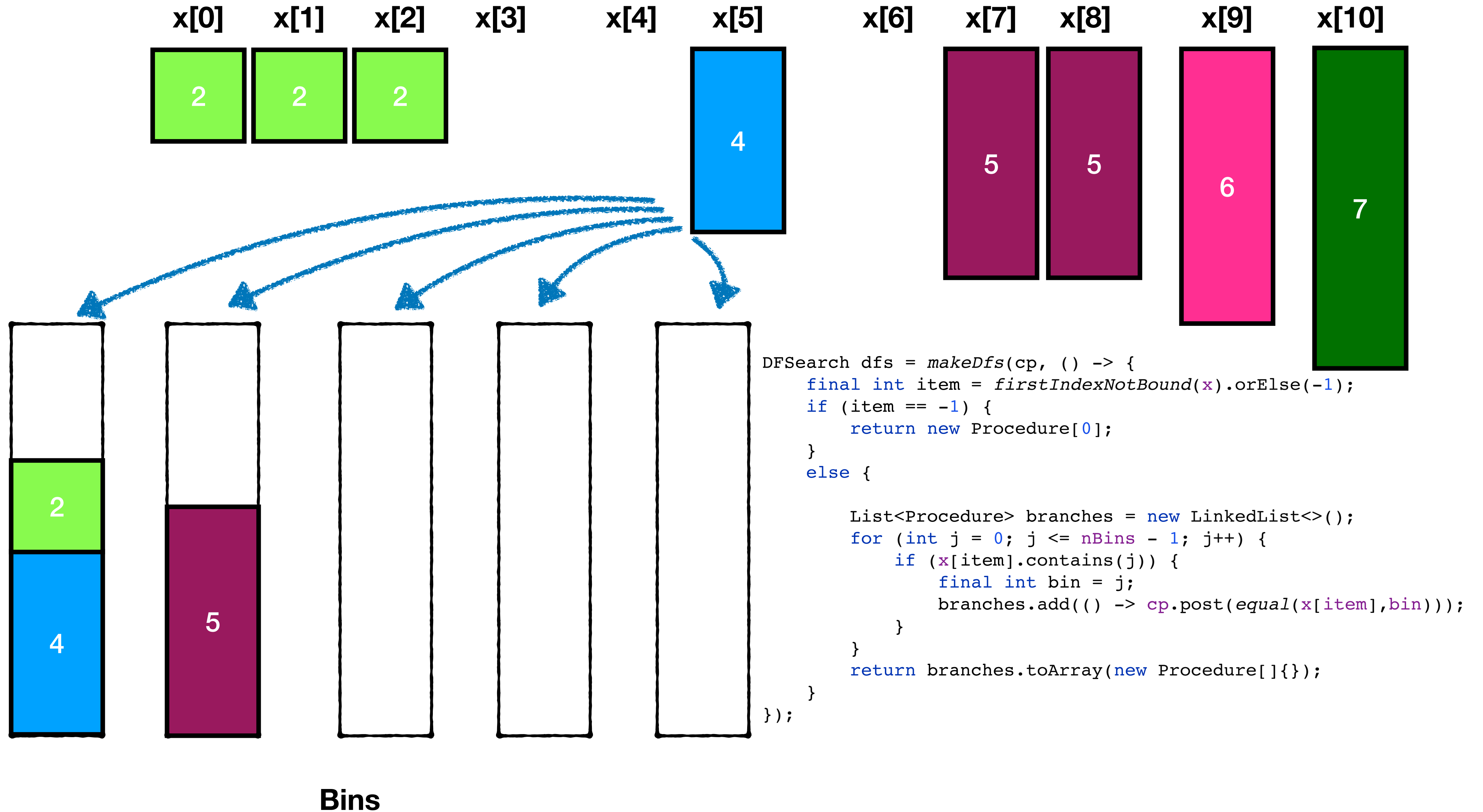
Drawback of symmetry breaking with constraints

- ▶  Sometimes useful, sometimes not
- ▶ Be careful because you suppress solutions.
- ▶ Consequence:
 - Solution discovered very early in the search tree might not exist anymore (bad interaction with the heuristic).

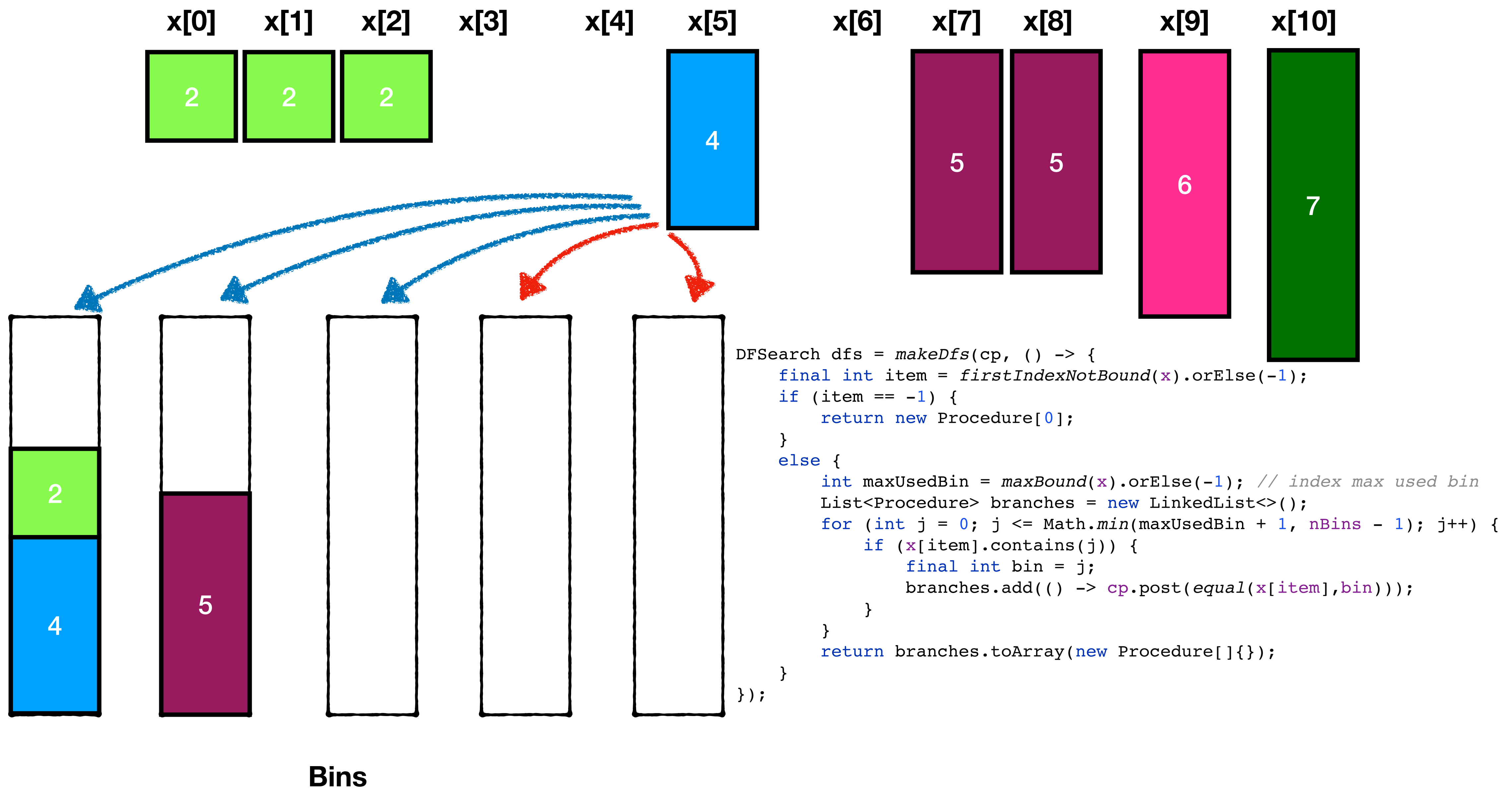


- ▶ Is it possible to remove variable/value symmetries such that the first solution remains the same ?
- ▶ Yes! Dynamic symmetry breaking = Add constraints **during search**
 - each time a (non-)solution is found)
 - Special search heuristic

Dynamic Symmetry Breaking during Search



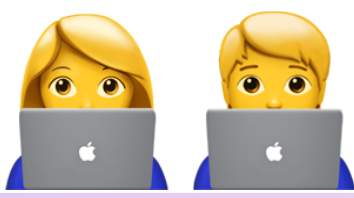
Dynamic Symmetry Breaking during Search



Symmetry breaking

- ▶ Static Symmetry Breaking
 - Use different variables
 - Add constraints to the model (ex: lexicographic)
- ▶ Dynamic Symmetry breaking (during search)
 - Add constraints during the search (each time a (non—solution is found)
 - Use special search heuristics
- ▶ Breaking symmetries does not always help (symmetries removed but so might be the left-most solution)

Bin-Packing Demo ...





Steel Mill Slab Problem

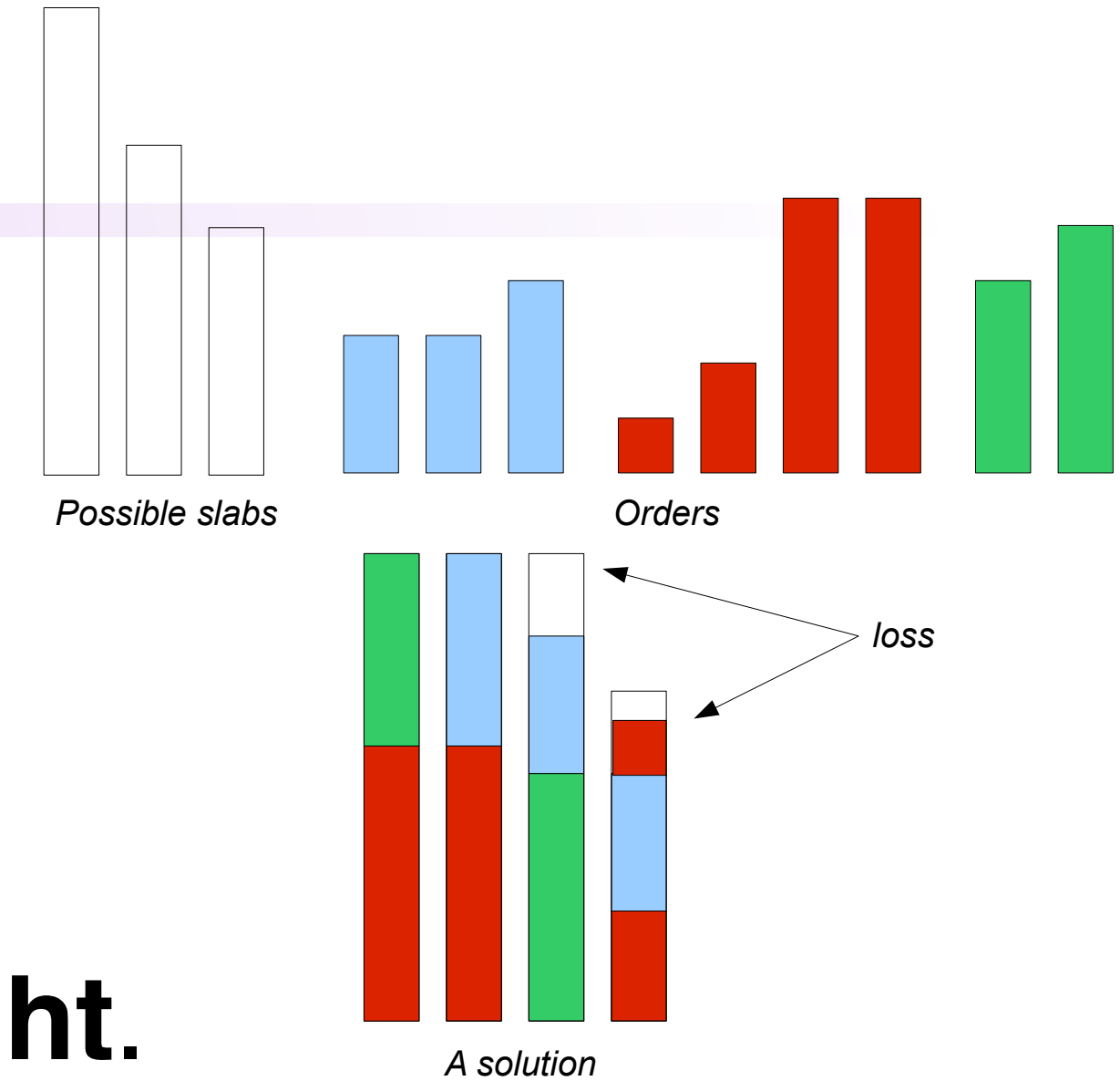
(Programming Assignment)

<https://www.csplib.org/Problems/prob038/>

The Steel Mill Slab Problem



- ▶ Steel produced by casting molten iron into slabs.
- ▶ Only a finite number of slab sizes.
- ▶ An order has two properties,
 - a **color** (route required through the steel mill) and + **weight**.
- ▶ Given n input orders, assign the orders to slabs, the number and size of which are also to be determined, such that **the total weight of steel produced is minimized**.
- ▶ Assignment subject to constraints:
 - Capacity: The total weight assigned to a slab cannot exceed the slab capacity.
 - Colors: Each slab can contain at most 2 colors.



Notations

- ▶ n is the number of orders
- ▶ $c_i \in \text{colors}$ is the color of order i
- ▶ $w_i \in \mathbb{N}^+$ is the weight of order i
- ▶ σ is the set of different slab capacity. At most m slabs will be used, we label them from 1 to m ($m = n$ if not restricted)

Model

► Decision variables:

- $o_i \in [1..n]$ is the slab attributed to order i

► Auxiliary variables:

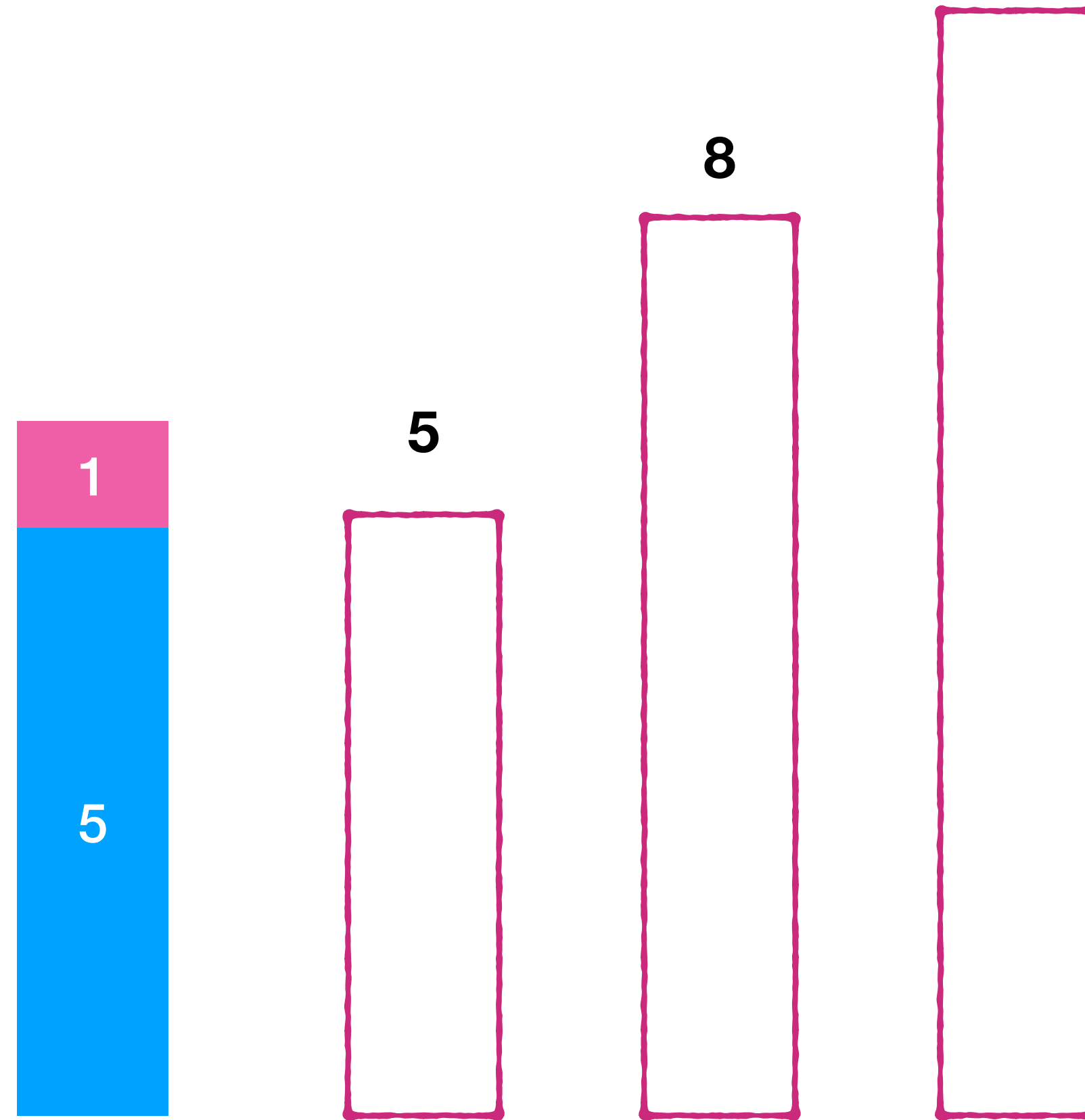
- $p_j \in [0..\text{maxcapa}]$ is the weight of the orders attributed to slab j
- $l_j \in [0..\text{maxcapa}]$ is the minimal loss of slab j (determined by the slab of minimal capacity $\geq p_j$)

► Objective

minimize the total loss:
$$\sum_{j \in [1..m]} l_j$$

Computing losses with Element Constraints

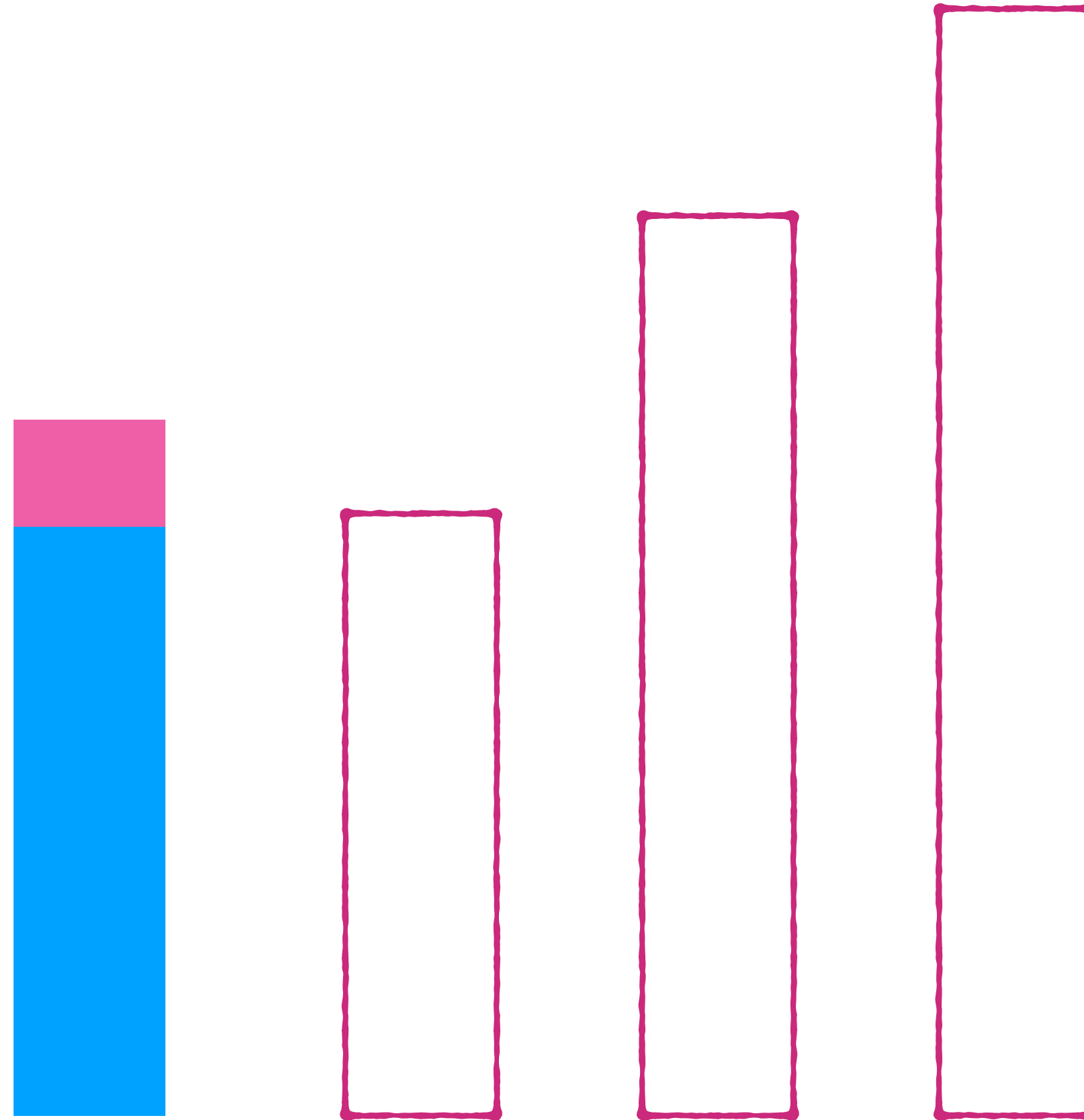
- ▶ Assume 3 slab capacities $\{5, 8, 10\}$, an order of size 5 and 1
- ▶ What slab to chose ? What is the loss ?



Computing losses with Element Constraints

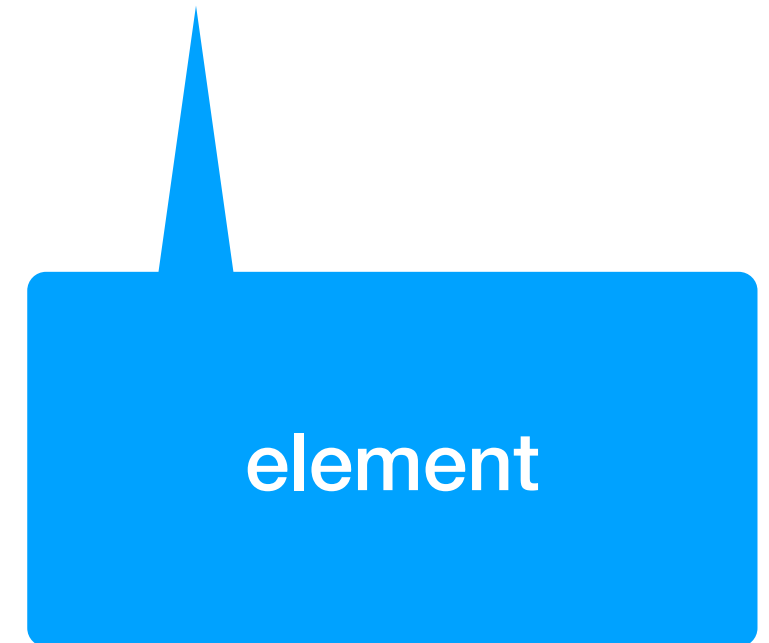
- ▶ 💡 precompute the loss for every possible load

Load	Loss
10	0
9	1
8	0
7	1
6	2
5	0
4	1
3	2
2	3
1	4
0	0



Computing losses with Element Constraints

- ▶ Assume 3 slab capacities $\{5, 8, 10\}$
- ▶ We can preprocess an array $L = [0, 4, 3, 2, 1, 0, 2, 1, 0, 1, 0]$.
- ▶ Loss for a total weight $p_j = 3$? $L = [0, 4, 3, 2, 1, 0, 2, 1, 0, 1, 0]$.
- ▶ 💡 Use element constraints to link loss and weight variables: $l_j = L[p_j]$



Computing loads (Bin-Packing or Pack)

$$\forall j \in [1..m] : p_j = \sum_{i \in [1..n]} (o_i = j) \cdot w_i$$





At most two colors!

Logical Or Constraint (and watched literals)

Modeling the Color Constraints

► At most 2 colors / slab

- Is color k used in slab j (yes 1, no 0)?

isOr constraint
b iff (x_1 or x_2 or ... or x_n)

$$\bigvee_{i \in [1..n] | c_i = k} (o_i = j)$$

isEqual

- $\forall j \in [1..n]$:

$$\sum_{k \in colors} \left(\bigvee_{i \in [1..n] | c_i = k} (o_i = j) \right) \leq 2.$$

isOr

Reified Or: IsOr Constraint

- ▶ b iff $(x_1 \text{ or } x_2 \text{ or } \dots \text{ or } x_n)$
 - $b = \text{true}$: post $(x_1 \text{ or } x_2 \text{ or } \dots \text{ or } x_n) =$ the Or constraint and deactivate
 - $b = \text{false}$: set all variables x_i to false
 - x_i become true: set b to true and deactivate (we must listen to all variables)
 - all x_i 's are false: set b to false (maintain them in a sparse-set)

The Or or Clause Constraint

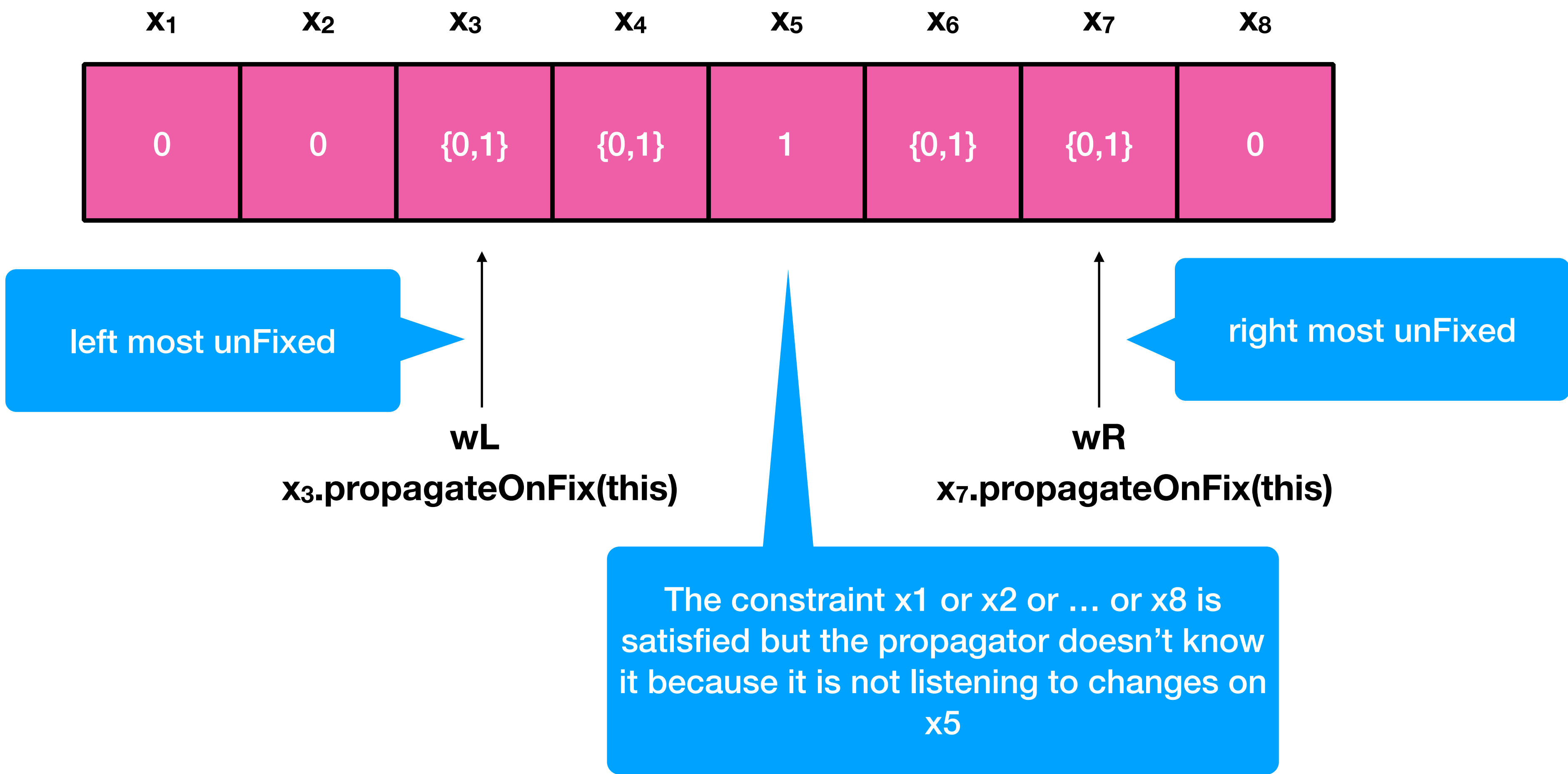
- ▶ At least one boolean variable is true:
 - x_1 or x_2 or ... or x_n
- Can only propagate when all variables are false, except one (this is called **unit propagation**).
- This is the only propagation used in modern SAT solvers.

First implementation

- ▶ Listen to all variables
- ▶ Maintain sparse-set with unbound variables
- ▶ If one variable become true, deactivate the constraint because it is satisfied.
- ▶ If the sparse-set becomes empty and all other variables are false, throw an InconsistencyException
- ▶ If only one variable is unbound, the other ones are false, set the last one to true (unit propagation)
- ▶ Can be done with $O(1)$ per variable change but can we do better?

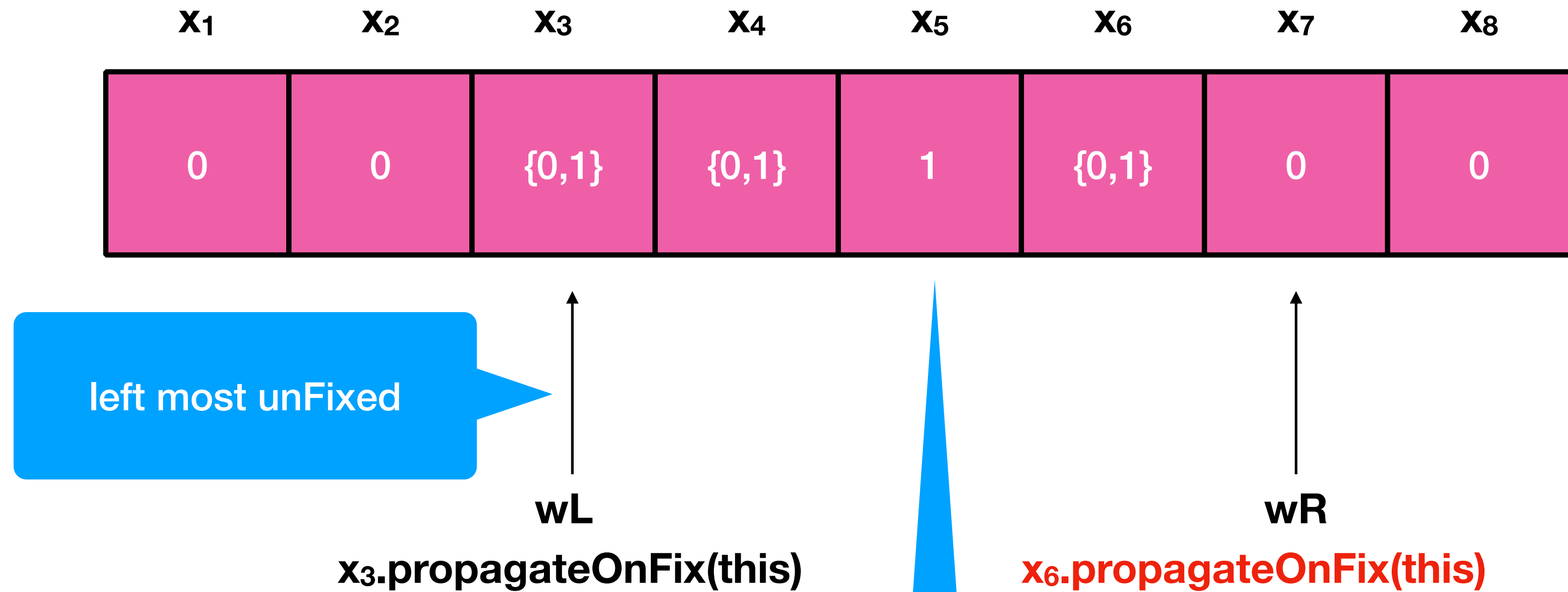
Watched literal (adapted to MiniCP)

- ▶ Don't listen to all changes, only listening to two variables is enough.
- ▶ Idea: If two variables are either unassigned or assigned true, no need to do anything.



Watched literal (adapted to MiniCP)

- ▶ Don't listen to all changes, only listening to two variables is enough



The constraint x₁ or x₂ or ...
 or x₈ is satisfied but the
 propagator doesn't know it
 because it is not listening to
 changes on x₅

Unit Propagation

- ▶ If $w_L = w_R$ (only one variable $\neq 0$), it must be set to 1
- ▶ If $w_L > w_R$, all variable are zero, we must fail (inconsistency).

Reified Or: IsOr Constraint

- ▶ b iff $(x_1 \text{ or } x_2 \text{ or } \dots \text{ or } x_n)$
 - $b = \text{true}$: post $(x_1 \text{ or } x_2 \text{ or } \dots \text{ or } x_n) =$ the Or constraint and deactivate
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 - all x_i 's are false: set b to false (maintain them in a sparse-set)

- ▶ Exercise: bijection on graph coloring for value symmetries
- ▶ Redundant constraints
- ▶ Static vs Dynamic symmetry breaking